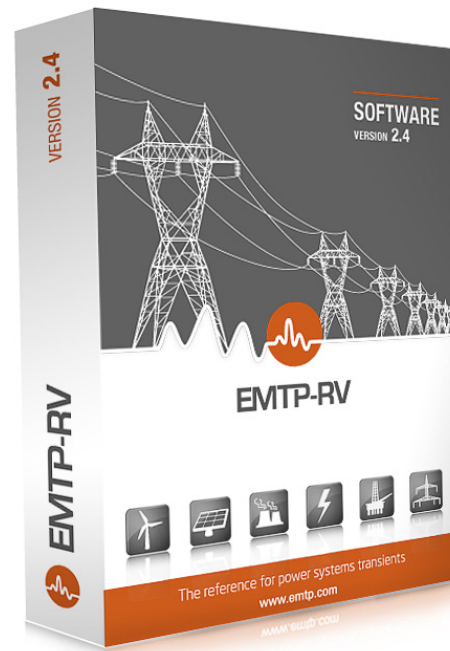




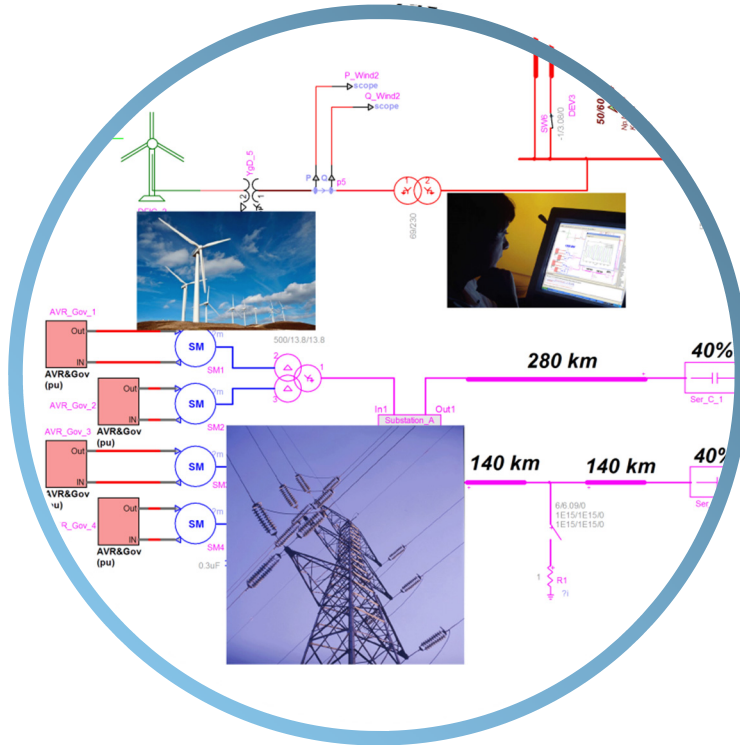
# An introduction to EMTP-RV

## The reference for power systems transients

August 2012

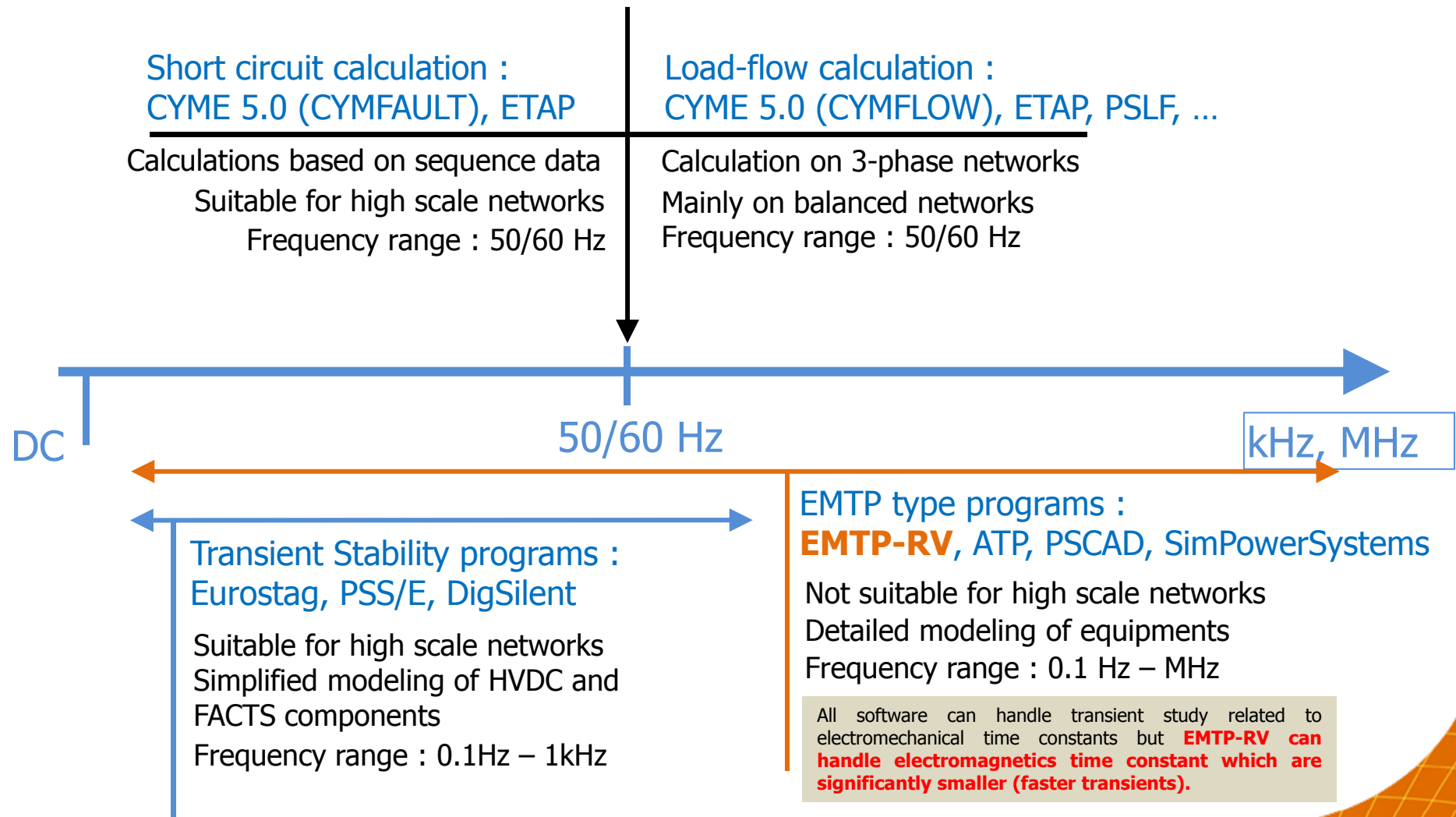
**powersys**  
solutions  
SOFTWARE & SERVICES

**EMTP-RV** 



The simulation of power systems has never been **so easy!**

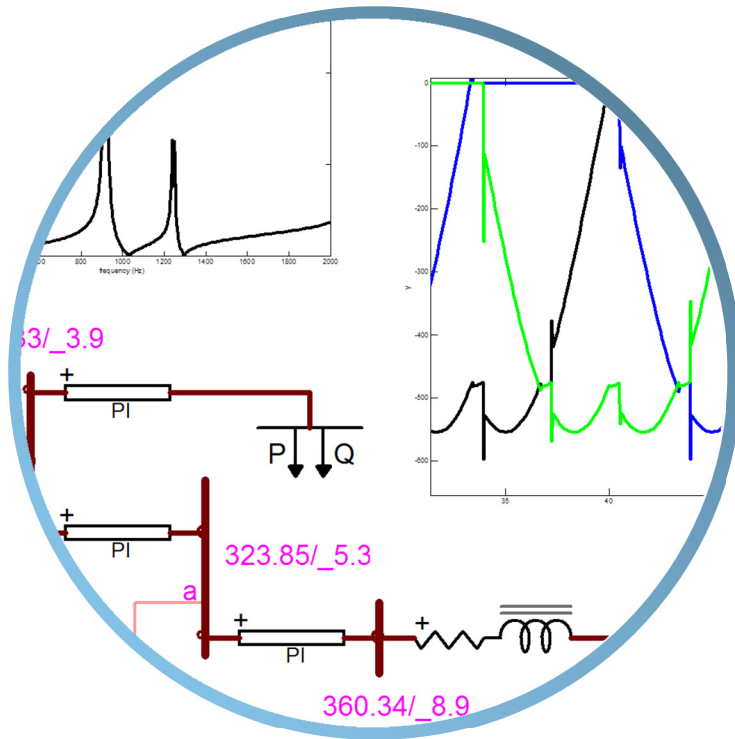
# Power system simulation tools



# EMTP-RV, the Restructured Version

- Written from scratch using mostly Fortran-95 in Microsoft Visual Studio environment.
- Include all the EMTP96 functionalities and much more:
  - 3-phase unbalanced load-flow
  - Scriptable user interface
  - New models : machines, nonlinear elements...
  - No topological restrictions
- New numerical analysis methods :
  - Newton-raphson solution method for nonlinear models
  - New three-phase load-flow
  - Simultaneous switching options for power electronics applications
  - Open architecture coding that allows users customization (ex : connection with user defined DLL)

## EMTP-RV benefits:



- Robust simulation engine
- Easy-to-use, drag and drop interface
- Unmatched ease of use
- Superior modeling flexibility
- Customizable to your needs
- Competitive pricing



## Customizable to your needs

- Superior modeling flexibility
  - Can't find exactly what you're looking for in the device library? Simply add your own user-defined device.
  - Scripting techniques provide the ability to externally program device data forms and generate the required Netlists. A symbol editor is used to modify and customize device drawings. Scripting techniques are also used for parametric studies.
  - EMTPWorks also lets the user define any number of subcircuits to create hierarchical designs.

# The software package

## EMTP-RV Package includes:

- EMTP-RV : computational engine

- With EMTP-RV, complex problems become simple to work out.

A powerful and super-fast computational engine that provides significantly improved solution methods for nonlinear models, control systems, and user-defined models. The engine features a plug-in model interface, allowing users to add their own models.

- EMTPWorks : Graphical User Interface

EMTPWorks, the user-friendly and intuitive Graphical User Interface, provides top-level access to EMTP-RV simulation methods and models.

**EMTPWorks** sends design data into EMTP-RV, starts EMTP-RV and retrieves simulation results.

An advanced, yet easy-to-use graphical user interface that maximizes the capabilities of the underlying EMTP-RV engine. EMTPWorks offers drag-and-drop convenience that lets users quickly design, modify and simulate electric power systems. A drawing canvas and the ability to externally program device data allows users to fully customize simulations to their needs. EMTPWorks can be used for small systems or very large-scale systems.

- ScopeView: the Output Processor for Data display and analysis

**ScopeView** displays simulation waveforms in a variety of formats.

With EMTPWorks, users can dramatically reduce the time required to setup a study in EMTP-RV.



# Key features

- EMTP-RV Key features

- **The reference in transients simulation**
- **Solution for large networks**
- Provide **detailed modeling of the network component** including control, linear and non-linear elements
- **Open architecture** coding that allows users customization and implementation of sophisticated models
- New **steady-state solution with harmonics**
- New three-phase **load-flow**
- **Automatic initialization** from steady-state solution
- New capability for **solving detailed semiconductor models**
- Simultaneous switching options for power electronics applications

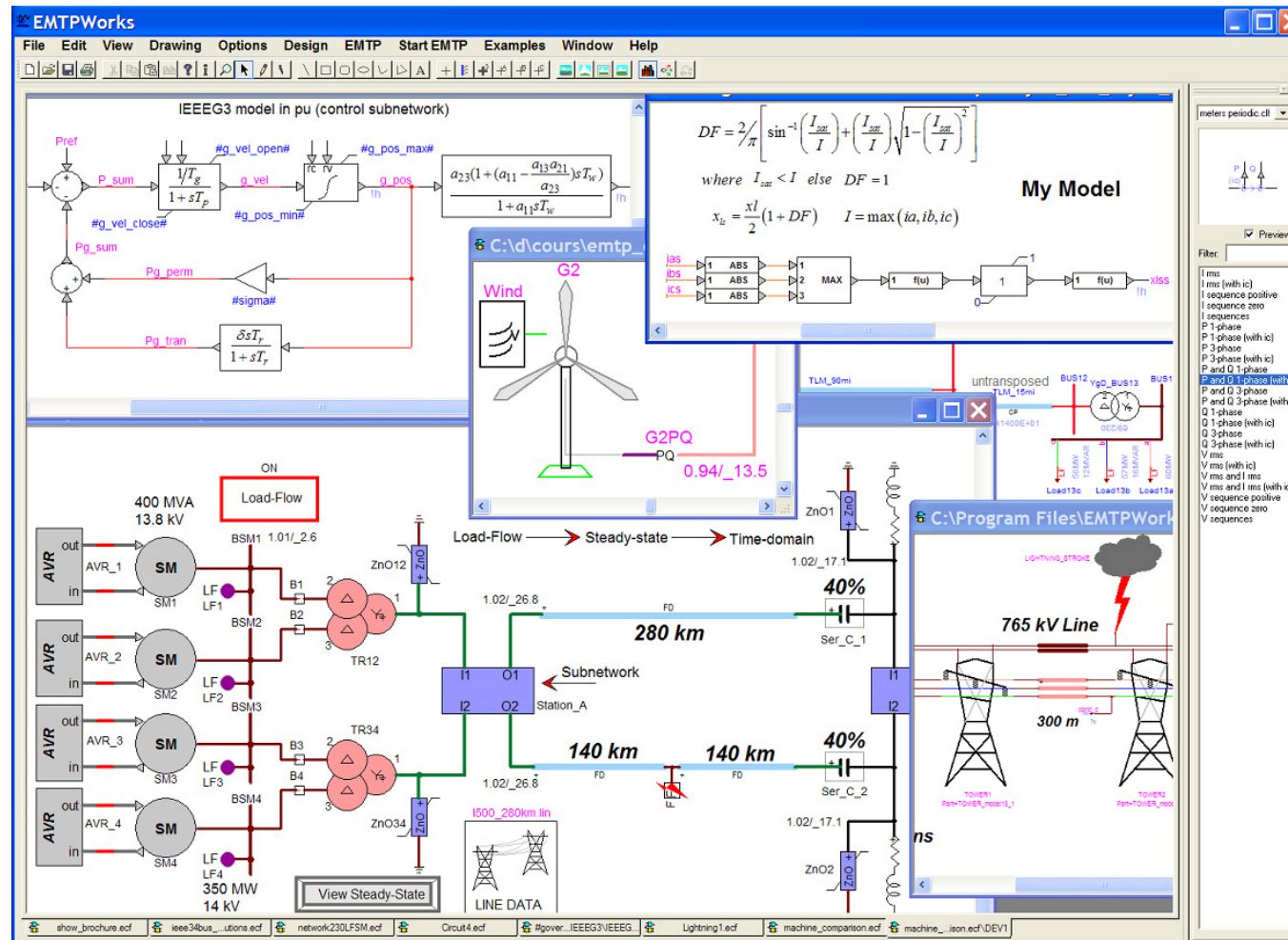


# The GUI key features

## EMTPWorks Key features

- Object-oriented design fully compatible with Microsoft Windows
- Powerful and intuitive interface for creating sophisticated Electrical networks
- Drag and drop device selection approach with simple connectivity methods
- Both devices and signals are objects with attributes. A drawing canvas is given the ability to create objects and customized attributes
- Single-phase/three-phase or mixed diagrams are supported
- Advanced features for creating and maintaining very large to extremely large networks
- Large number of subnetwork creation options including automatic subnetwork creation and pin positioning. Unlimited subnetwork nesting level
- Options for creating advanced subnetwork masks
- Multipage design methods
- Library maintenance and device updating methods

# EMTPWorks: EMTP-RV user interface



EMTP-RV

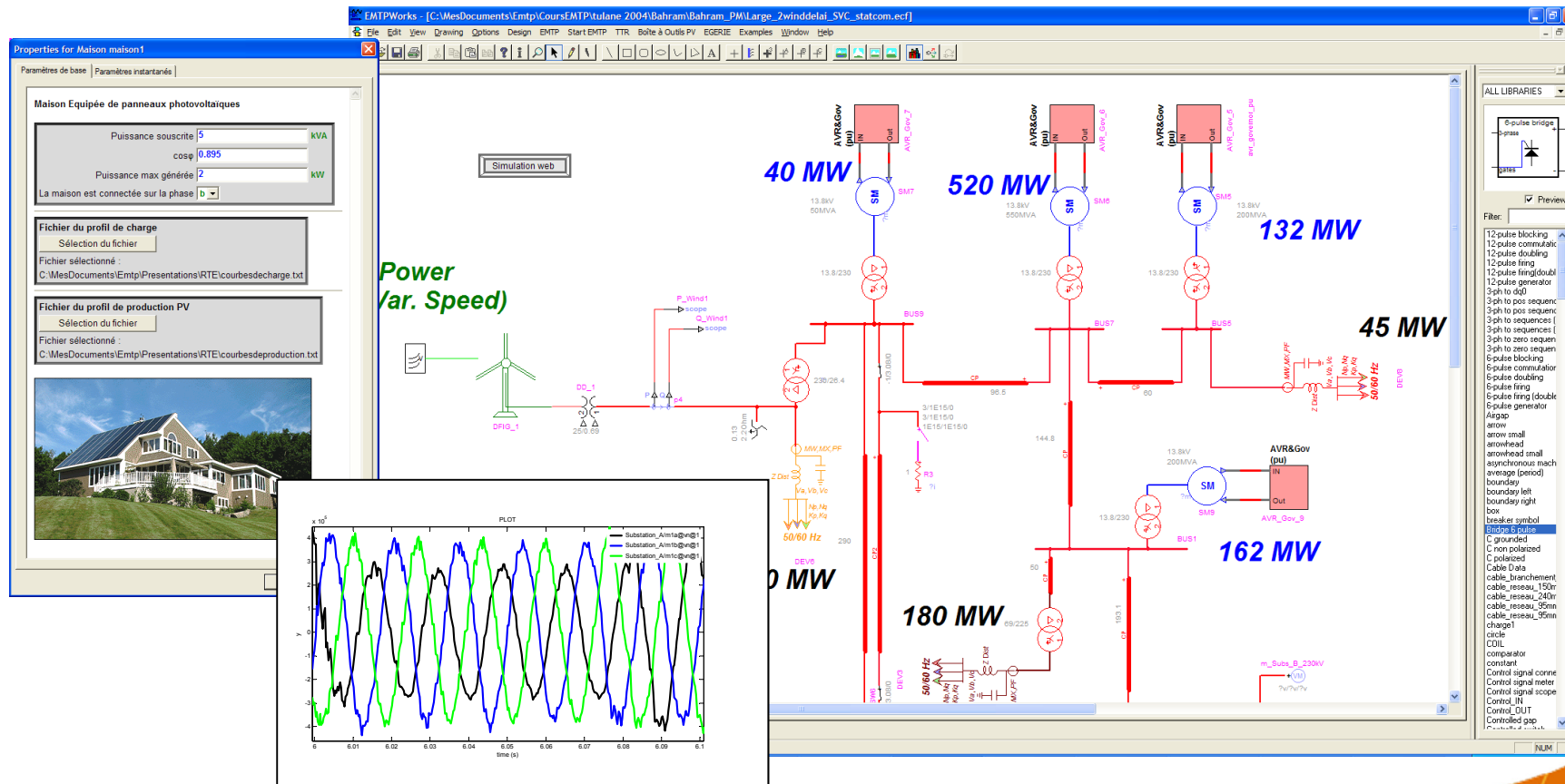


# EMTPWorks: EMTP-RV user interface

Object-oriented design fully compatible with Microsoft Windows

Single-phase/three-phase or mixed diagrams are supported

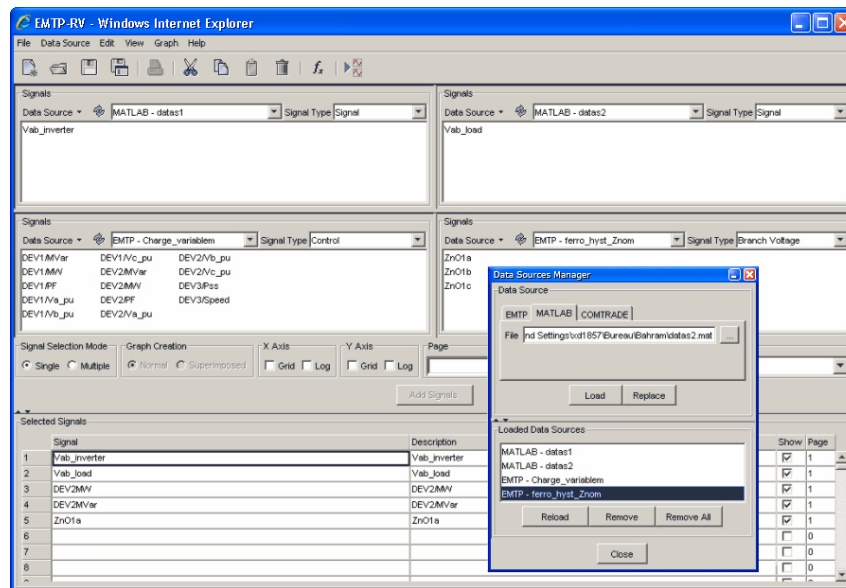
Large collection of scripts for modifying and/or updating almost anything appearing on the GUI



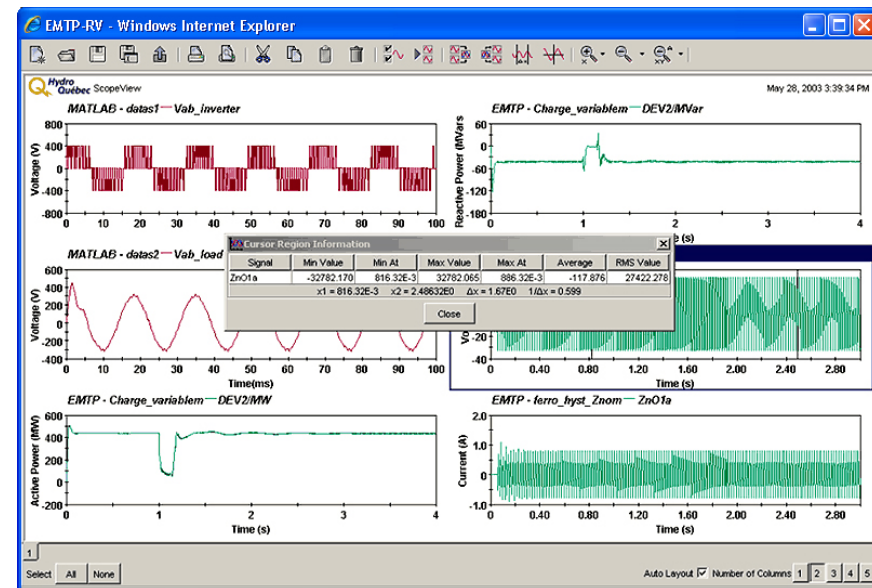


# ScopeView

ScopeView is a data acquisition and signal processing software adapted very well for visualisation and analysis of EMTP-RV results. It may be used to simultaneously load, view and process data from applications such as EMTP-RV, MATLAB and Comtrade format files.

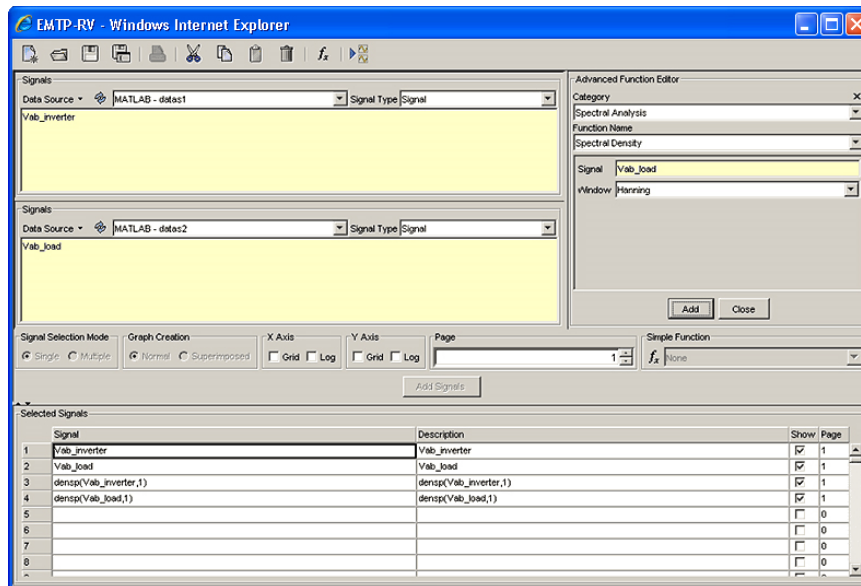


Multi-source data importation

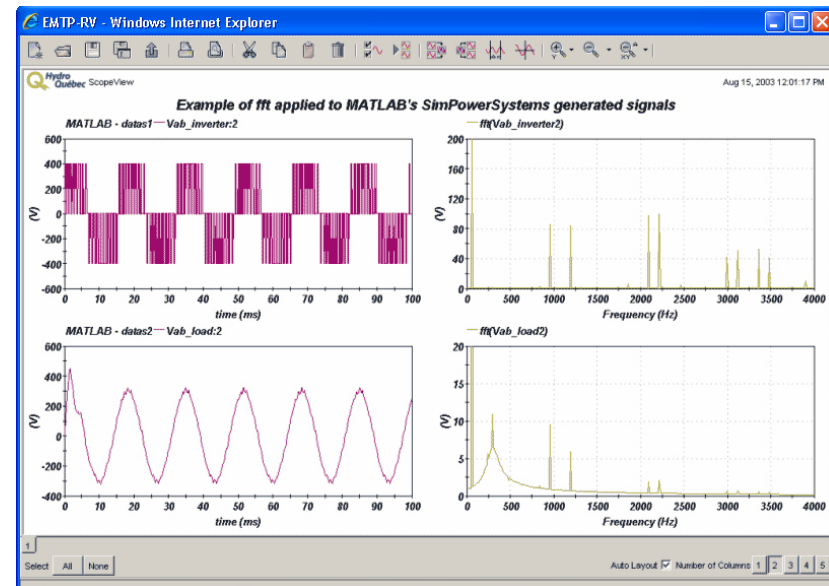


Cursor region information

# ScopeView



Function editor of ScopeView



Typical mathematical post-processing





EMTP-RV offers a wide variety of modeling capabilities encompassing electromagnetic and electromechanical oscillations ranging in duration from microseconds to seconds.

# A powerful power system simulation software

## EMTP-RV's benefits are:

Unmatched ease of use

Superior modeling flexibility

Customizable to your needs

Dynamic development road-map

Prompt and effective technical support

Reactive sales teams



# A powerful power system simulation software

## EMTP-RV's strengths:

Used worldwide as a reference tool by the main actors of the power system industry since many years (EDF, Hydro-Québec, RTE and many other utilities, manufacturers, consultants...),

Large field of power systems applications,

Numerical robustness and stability,

Comprehensive built-in libraries including detailed models of electrical machines, transformers, lines, cables, ...

Automatically initializes time-domain simulations from steady-state,

Capability to simulate very large power systems and power electronics systems without compromising precision,

The most advanced user-defined modeling capabilities using DLLs and devices in the GUI,

The same design can be used for load-flow, steady-state, time-domain and frequency scan simulation,

Scriptable and customizable easy-to-use GUI,

Many application examples are provided with EMTP-RV,

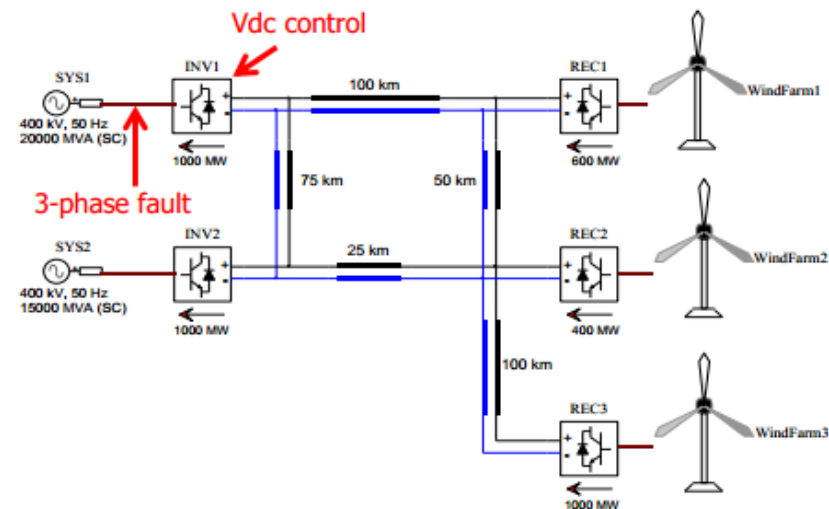
Reactive and efficient technical support,

Competitive pricing.



## EMTP-RV version 2.4 new features:

- New and advanced **HVDC models**, including MMC-HVDC
- New **wind generator models**, including average-value model
- New **control system diagram DLL capability**
- New Simulink/Real-time Workshop interface DLL





## EMTP-RV version 2.4 improvements:

Workshop interface DLL

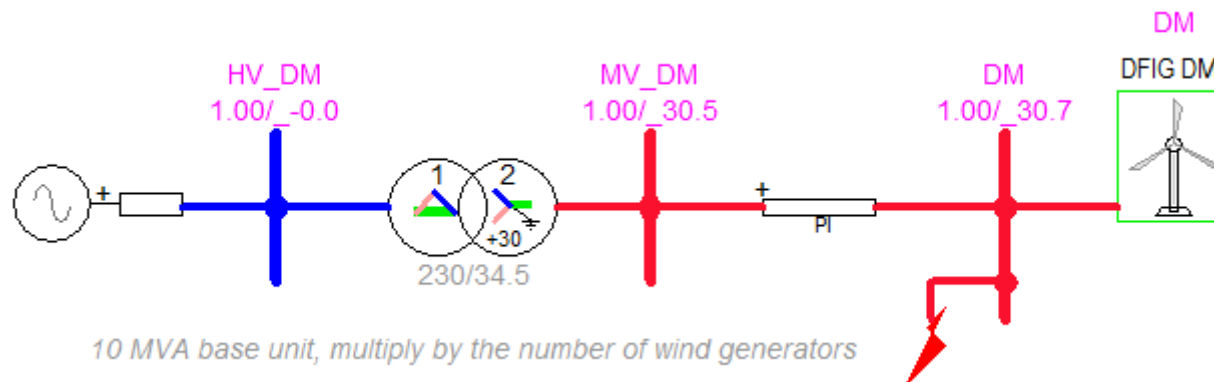
Improvements in synchronous machine model including a new black start option

Improvements in the asynchronous machine model

Capability to solve multiple frequency load-flow

Improved documentation and various other improvements

### New application examples



# Power system studies

EMTP-RV is suited to a wide variety of power system studies including and not limited to:

- Power system design
- Power system stability & load modeling
- Control system design
- Motor starting
- Power electronics and FACTS
- HVDC networks
- Lighting surges
- Switching surges
- Temporary overvoltages
- Insulation coordination
- Complete network analysis
- Ferroresonance
- Steady-state analysis of unbalanced system
- Distribution networks and distributed generation
- Power system dynamic and load modeling
- Subsynchronous resonance and shaft stresses
- Power system protection issues
- General control system design
- Power quality issues
- Capacitor bank switching
- And much more!

# A versatile program

## Complete system studies:

- Load-flow solution and initialization of synchronous machines
- Temporary overvoltages to network islanding
- Ferroresonance and harmonic resonance
- Selection and usage of arresters
- Fault transients
- Statistical analysis of overvoltages
- Electromechanical transients

# Applications

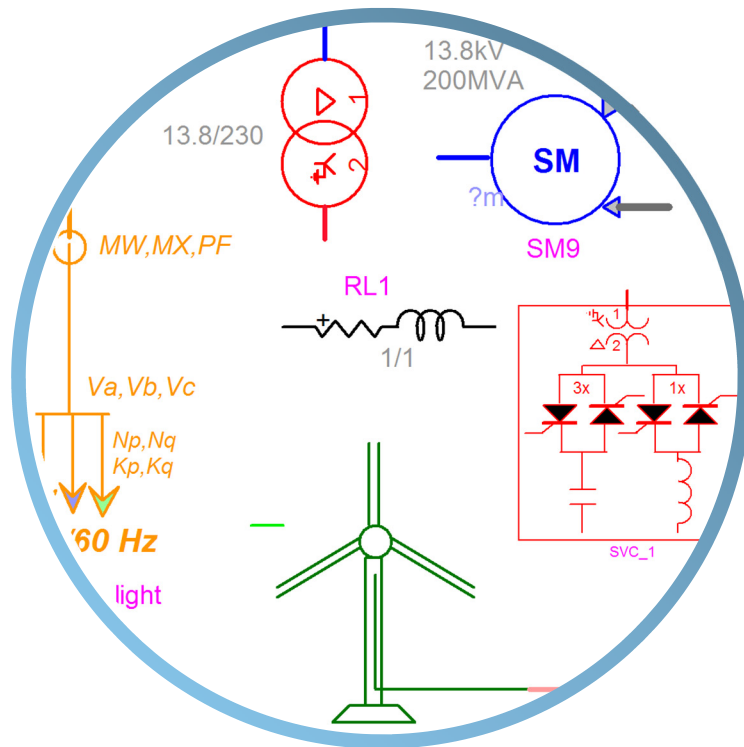
- **Power system design**
- Power systems protection issues
- **Network analysis:** network separation, power quality, geomagnetic storms, interaction between compensation and control components, wind generation
- Detailed simulation and analysis of **large scale** (unlimited size) **electrical systems**
- Simulation and analysis of **power system transients:** lightning, switching, temporary conditions
- General purpose **circuit analysis:** wideband, from load-flow to steady-state to time-domain (Steady-state analysis of unbalanced systems)
- **Synchronous machines:** SSR, auto-excitation, control
- **Transmission line systems:** insulation coordination, switching, design, wideband line and cable models



# Applications

- **Power Electronics and FACTS** (HVDC, SVC, VSC, TCSC, etc.)
- Multiterminal **HVDC systems**
- **Series compensation**: MOV energy absorption, short-circuit conditions, network interaction
- **Transmission line systems: insulation coordination**, switching, design, wideband line and cable models
- **Switchgear**: TRV, shunt compensation, current chopping, delayed-current zero conditions, arc interaction
- **Protection**: power oscillations, saturation problems, surge arrester influences
- **Temporary overvoltages**
- **Capacitor bank switching**
- **Series and shunt resonances**
- **Detailed transient stability analysis**
- **Unbalanced distribution networks**





# Simulation options

Load-flow

Steady-state

Time-domain

Frequency scan



# Simulation options

- **Load-Flow solution**

- The electrical network equations are solved using complex phasors.
- The active (source) devices are only the Load-Flow devices (LF-devices). A load device is used to enter PQ load constraint equations.
- Only single (fundamental) frequency solutions are achievable in this version. The solution frequency is specified by 'Default Power Frequency' and used in passive network lumped model calculations.
- The same network used for transient simulations can be used in load-flow analysis. The EMTP Load-Flow solution can work with multiphase and unbalanced networks.
- The control system devices are disconnected and not solved.
- This simulation option stops and creates a solution file (Load-Flow solution data file). The solution file can be loaded for automatically initializing anyone of the following solution methods.

# Simulation options

- Steady-state solution

- The electrical network equations are solved using complex numbers. This option can be used in the stand-alone mode or for initializing the time-domain solution.
- A harmonic steady-state solution can be achieved.
- The control system devices are disconnected and not solved.
- Some nonlinear devices are linearized or disconnected. All devices have a specific steady-state model.
- The steady-state solution is performed if at least one power source device has a start time (activation time) lower than 0.



# Simulation options

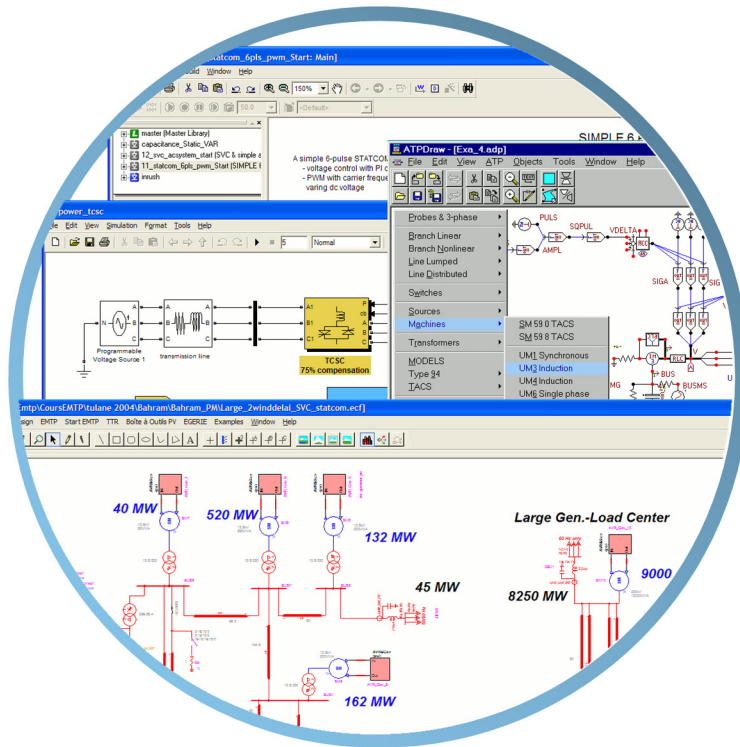
- Time-domain solution

- The electrical network and control system equations are solved using a numerical integration technique.
- All nonlinear devices are solved simultaneously with network equations. A Newton method is used when nonlinear devices exist.
- The solution can optionally start from the steady-state solution for initializing the network variables and achieving quick steady-state conditions in time-domain waveforms.
- The steady-state conditions provide the solution for the time-point  $t=0$ . The user can also optionally manually initialize state-variables.

## Simulation options

- Frequency scan solution
  - This option is separate from the two previous options. All source frequencies are varied using the given frequency range and the network steady-state solution is found at each frequency.





Build-in libraries and  
Standard models  
available in EMTP-RV

# Built-in libraries

| EQUIPMENT                   | FEATURES                                                                                                                                                                                               |
|-----------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| advanced.clf                | Provides a set of advanced power electronic devices                                                                                                                                                    |
| Pseudo Devices.clf          | Provides special devices, such as page connectors. The port devices are normally created using the menu "Option>Subcircuit>New Port Connector", they are available in this library for advanced users. |
| RLC branches.clf            | Provides a set of RLC type power devices. .                                                                                                                                                            |
| Work.clf                    | This is an empty library accessible to users                                                                                                                                                           |
| control.clf                 | The list of primitive control devices.                                                                                                                                                                 |
| control devices of TACS.clf | This control library is provided for transition from EMTP-V3. It imitates EMTP-V3 TACS functions.                                                                                                      |
| control functions.clf       | Various control system functions.                                                                                                                                                                      |
| control of machies.clf      | Exciter devices for power system machines.                                                                                                                                                             |
| flip flops.clf              | A set of flip-flop functions for control systems.                                                                                                                                                      |
| hvdc.clf                    | Collection of dc bridge control functions. Documentation is available in the subcircuit.                                                                                                               |
| lines.clf                   | Transmission lines and cables.                                                                                                                                                                         |
| machines.clf                | Rotating machines.                                                                                                                                                                                     |
| meters.clf                  | Various measurement functions, including sensors for interfacing control device signals with power device signals.                                                                                     |
| meters periodic.clf         | Meters for periodic functions.                                                                                                                                                                         |
| nonlinear.clf               | Various nonlinear electrical devices.                                                                                                                                                                  |
| options.clf                 | EMTP Simulation options, plot functions and other data management functions.                                                                                                                           |
| phasors.clf                 | Control functions for manipulating phasors.                                                                                                                                                            |
| sources.clf                 | Power sources.                                                                                                                                                                                         |
| switches.clf                | Switching devices.                                                                                                                                                                                     |
| symbols.clf                 | These are only useful drawing symbols, no pins.                                                                                                                                                        |
| transformations.clf         | Mathematical transformations used in control systems.                                                                                                                                                  |
| transformers.clf            | Power system transformers.                                                                                                                                                                             |



## Standard models

| Library             | Models                                                                                                                |
|---------------------|-----------------------------------------------------------------------------------------------------------------------|
| RLC branches        | R, L, C branches<br>PI circuits<br>Loads<br>State space block                                                         |
| Control             | Gain, constant<br>Integral, derivative<br>Limiter,<br>Sum<br>Selector<br>Delay<br>State-space block<br>PLL...         |
| Control of Machines | IEEE excitation systems<br>Governor / turbine                                                                         |
| Flip flops          | Flip-flop D, J-K, S-R,T                                                                                               |
| Lines               | CP (distributed parameters)<br>FD (=CP + frequency dependence)<br>FDQ (=FD for cables)<br>WB (phase domain)<br>Corona |



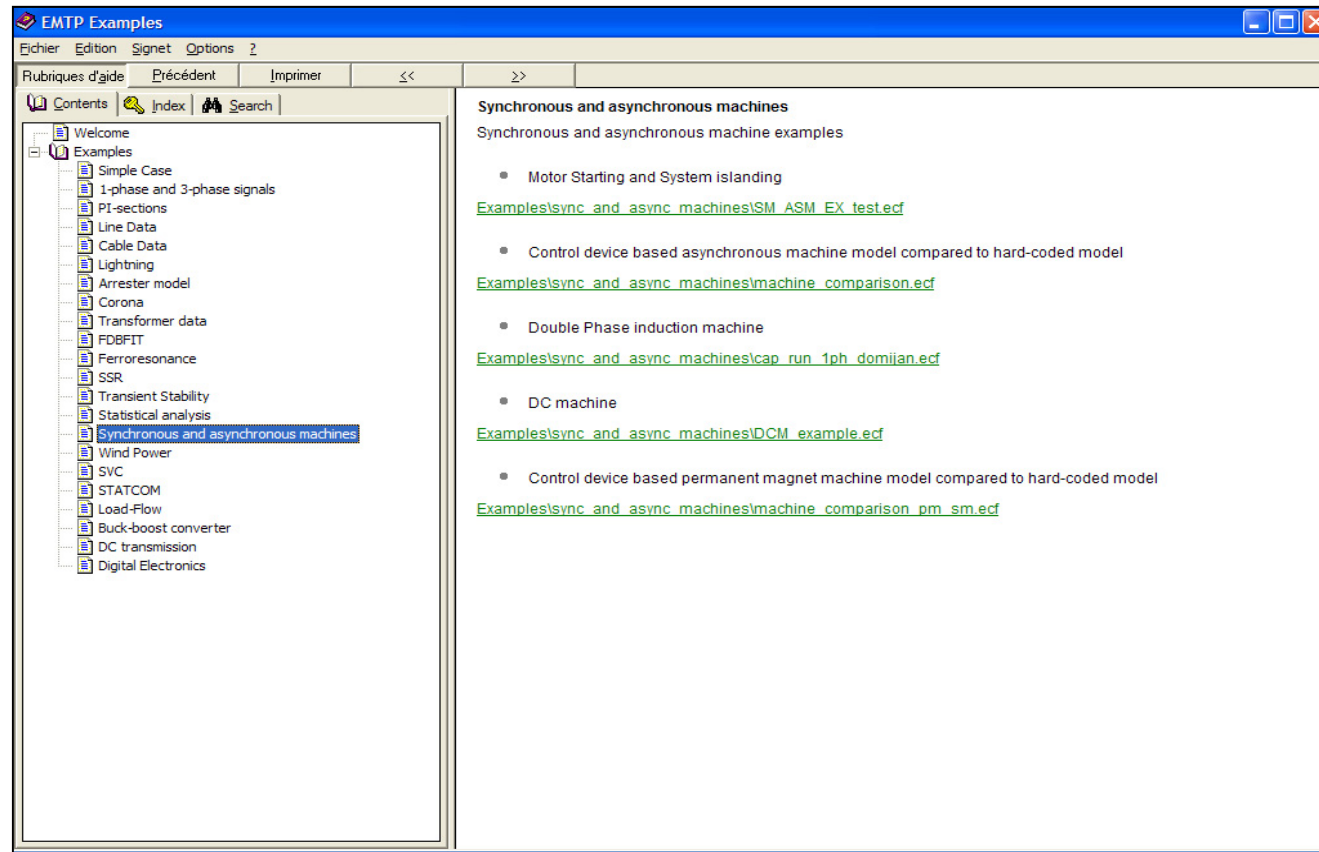
# Standard models

| Library         | Models                                                                                                                                                    |
|-----------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------|
| Machines        | Induction Machine (single cage, double cage, wound rotor)<br>Synchronous Machine<br>Permanent Magnet Synchronous Machine<br>DC machine<br>2-phase machine |
| Meters          | Current, voltage, power meters                                                                                                                            |
| Meters periodic | RMS meters and sequence meters                                                                                                                            |
| Nonlinear       | Non linear resistance<br>Non linear inductance<br>Hysteresis reactor<br>ZnO arrester<br>SiC arrester                                                      |
| Sources         | AC, DC voltage sources<br>AC, DC current sources<br>Lightning impulse current source<br>Current and voltage controlled sources<br>Load-flow bus           |

## Standard models

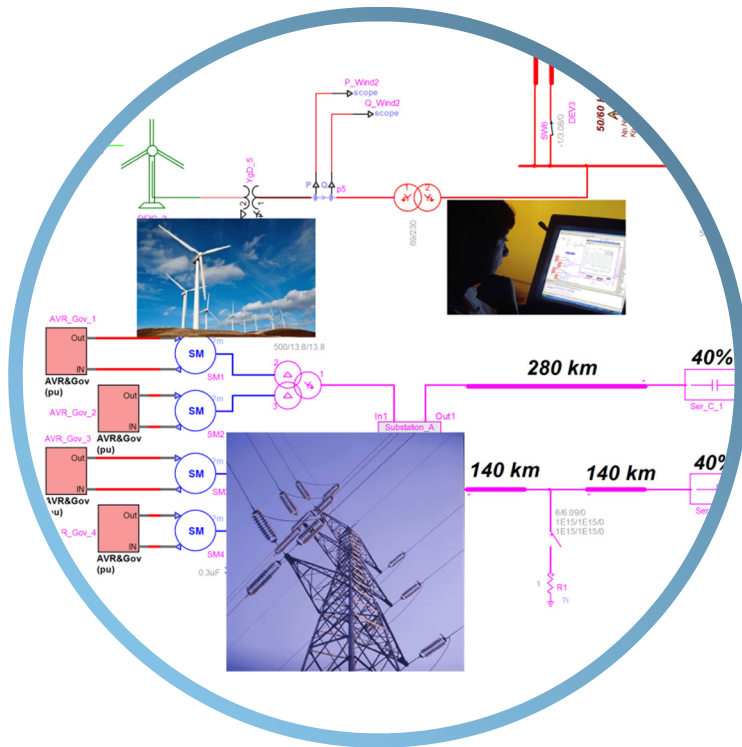
| Library         | Models                                                                                                                                                                     |
|-----------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Switches        | Ideal switch<br>Diode<br>Thyristor<br>Air gap                                                                                                                              |
| Transformations | 3-phase <-> sequence<br>3-phase <-> dq0                                                                                                                                    |
| Transformateurs | Based on single phase units : DD, YY, DY, YD, YYD...<br>Topological models : TOPMAG<br>Impedance based : BCTTRAN, TRELEG<br>Frequency dependent admittance matrix : FDBFIT |
| Advanced        | Variable load<br>SVC<br>STATCOM                                                                                                                                            |

# Built-in library of examples



Easily find what you're looking for by browsing or using a simple index.



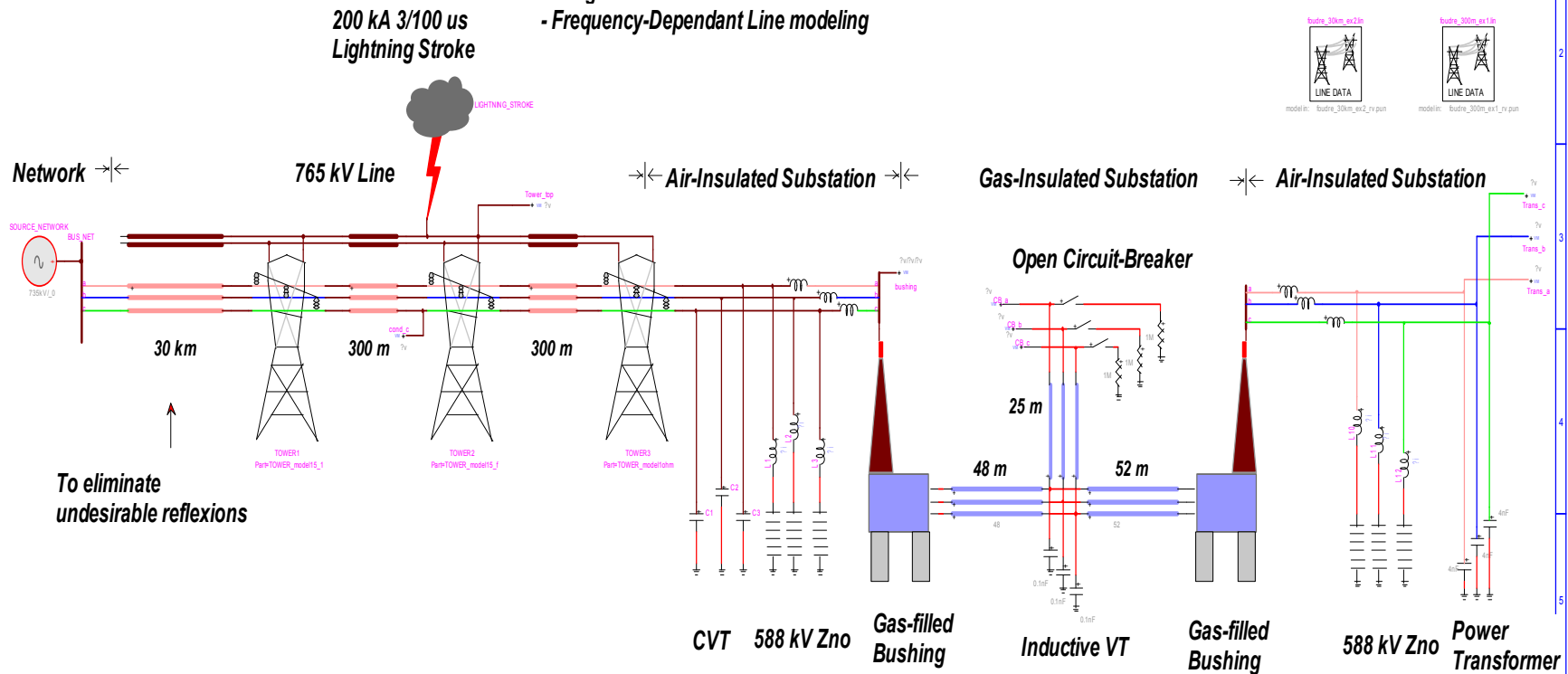


# Typical designs

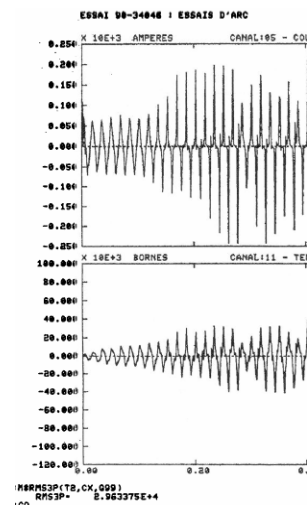
Modeling Electrical  
Systems with EMTP-RV

## Insulation Coordination of a 765 kV GIS

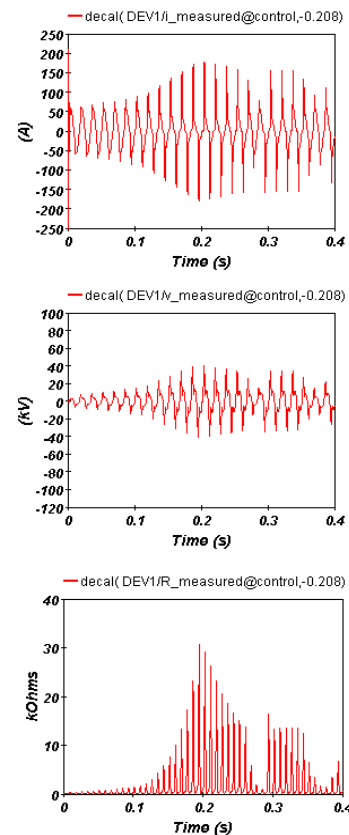
- Backflashover Case
- Impulse Footing Resistance of the stricken Tower may be represented by  $R_i = f(l)$
- Usage of ZnO model based on IEEE SPD WG
- Frequency-Dependant Line modeling



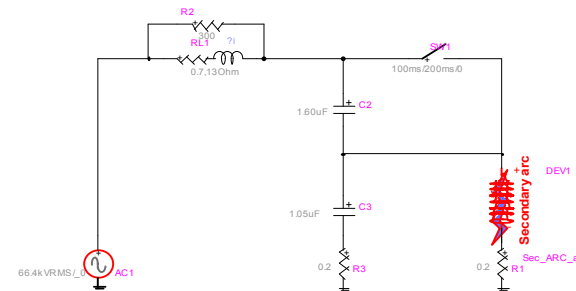
### Field Recording (10-08-1986)



### EMTP-RV Simulation (05-22-2005)



### Validation of the Secondary Arc Model with IREQ Laboratory Tests



**Primary Arc: 5 kA eff**  
**Secondary Arc: 40 A**  
**Wind Speed: 9.7 km/h**  
**Secondary Arc Duration: 1.04 sec.**  
**315 kV insulator string, l=2.3 m**

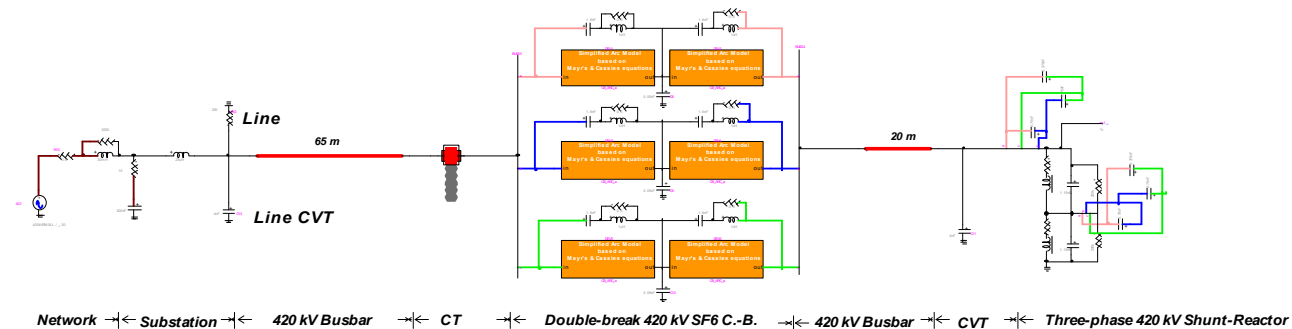
I/O FILES

## Switching of A 420 kV Three-Phase Shunt-Reactor

10/25/08

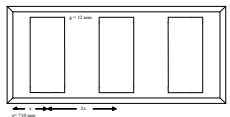
State of the art simulation introducing:

- A realistic model of a three-phase shunt reactor taking into account the asymmetrical couplings of the magnetic circuit;
- A realistic circuit-breaker model based on the well-known Cassie - Mayr modified arc equations.



Three-Phase 420 kV 100 MVARs Shunt Reactor

$F = 0.548 \text{ Wb}$ ,  $N = 1409 \text{ turns}$ ,  $L = 5.617 \text{ H}$

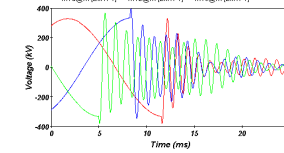
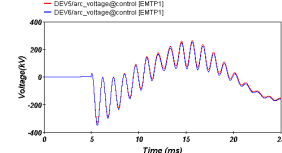
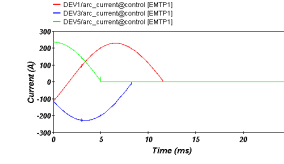
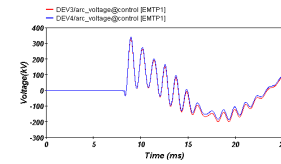
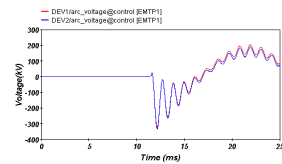


For  $\mu$  (50 Hz) = 0.06 H/m:

|                            |
|----------------------------|
| $X_{\text{ac0Caa}}$ 9 Ohms |
| $X_{\text{ac0Cab}}$ 9 Ohms |
| $X_{\text{ac0Cba}}$ 9 Ohms |
| $X_{\text{ac0Cbb}}$ 9 Ohms |
| $X_{\text{ac0Caa}}$ 9 Ohms |
| $X_{\text{ac0Cab}}$ 9 Ohms |
| $X_{\text{ac0Cba}}$ 9 Ohms |
| $X_{\text{ac0Cbb}}$ 9 Ohms |

For  $\mu$  (700 Hz) = 0.01 H/m:

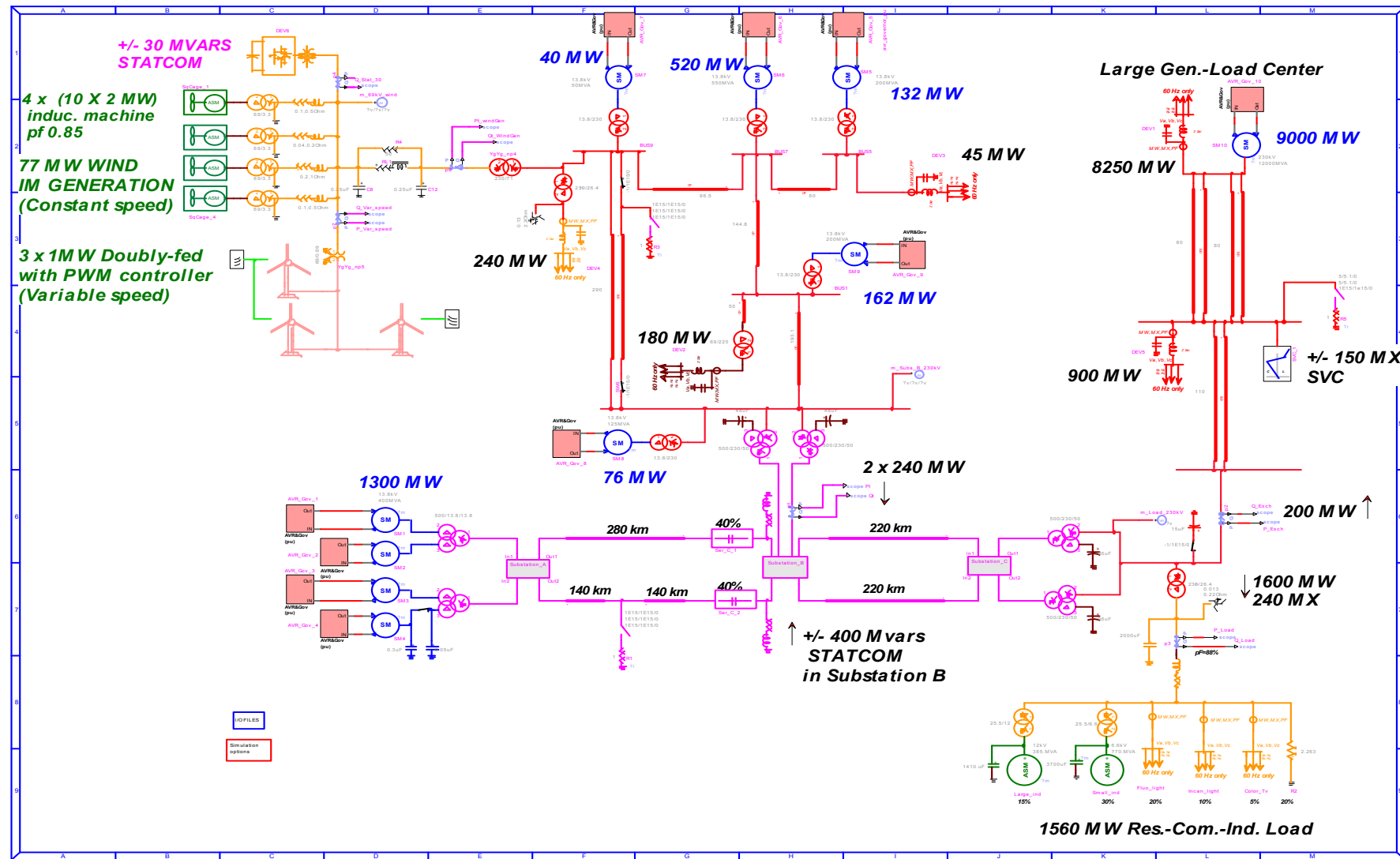
|                             |
|-----------------------------|
| $X_{\text{ac0Caa}}$ 54 Ohms |
| $X_{\text{ac0Cab}}$ 54 Ohms |
| $X_{\text{ac0Cba}}$ 54 Ohms |
| $X_{\text{ac0Cbb}}$ 54 Ohms |
| $X_{\text{ac0Caa}}$ 54 Ohms |
| $X_{\text{ac0Cab}}$ 54 Ohms |
| $X_{\text{ac0Cba}}$ 54 Ohms |
| $X_{\text{ac0Cbb}}$ 54 Ohms |



EMTP-RV







EMTP-RV

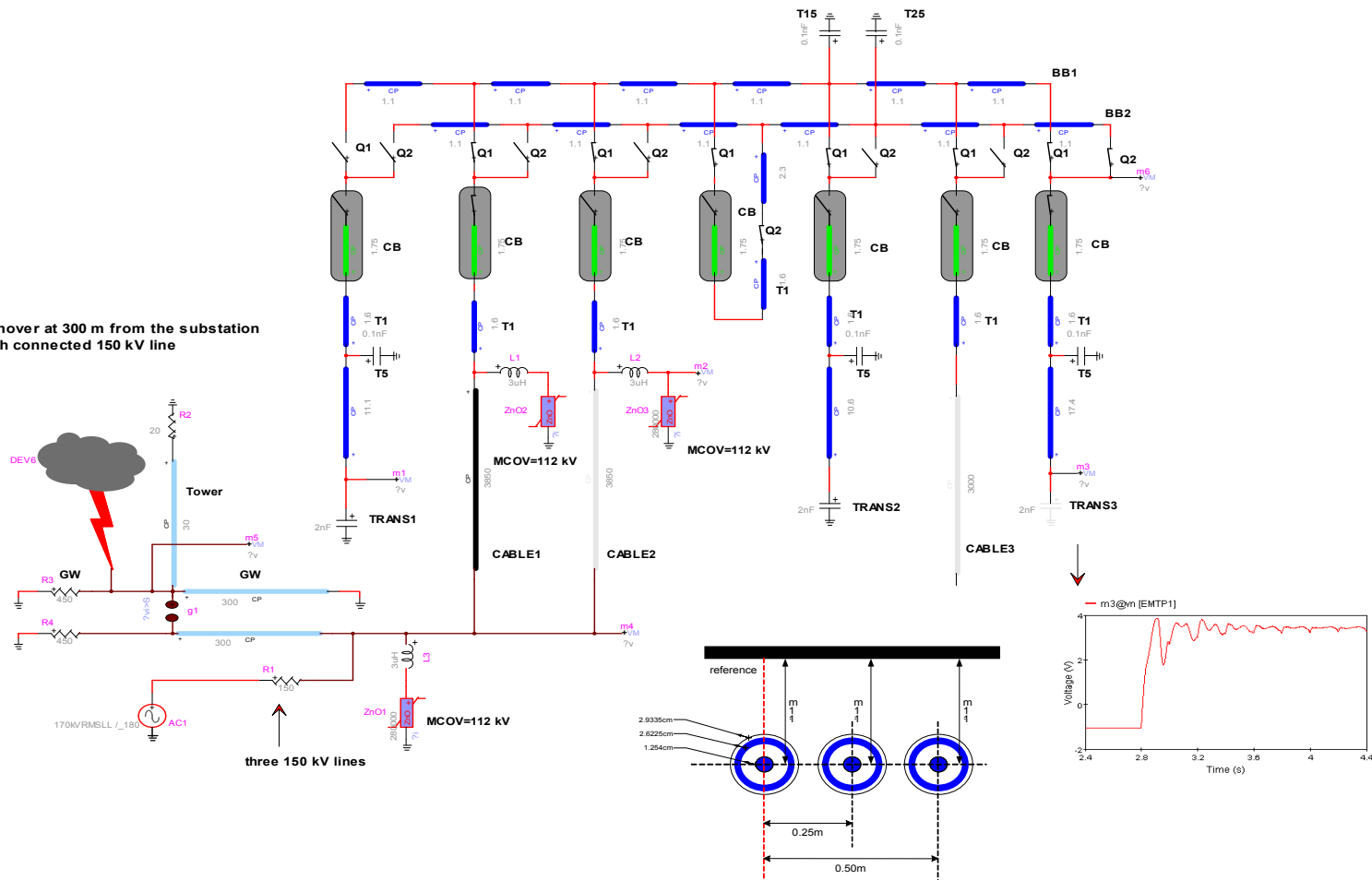


- **Realistic Wind Data;**
- **Realistic DFIG Modeling;**
- **Realistic Network & Load Models**
- **Realistic Harmonic Distorsions & Dynamic Performances**

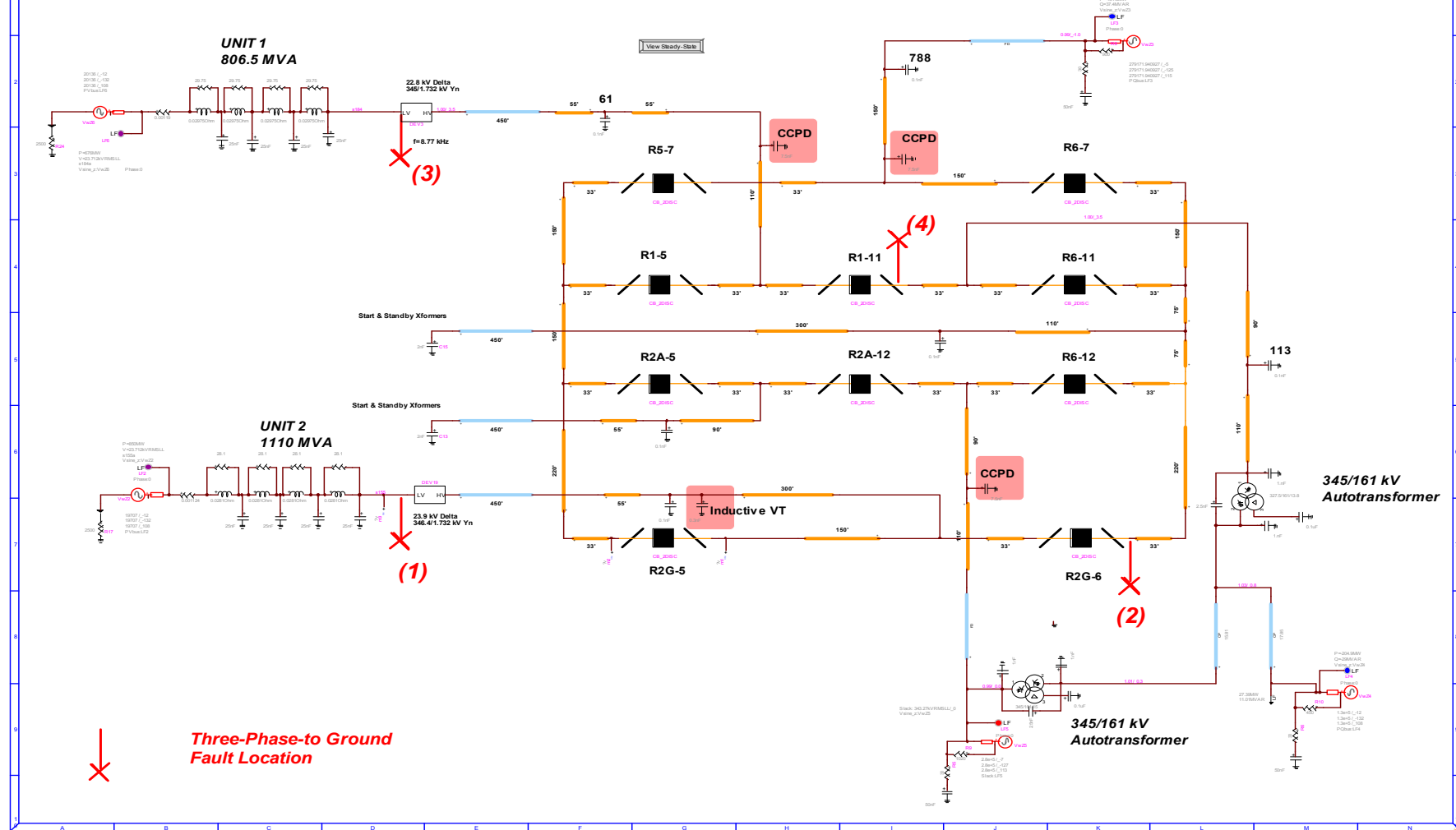


# Insulation Coordination of a 150 kV GIS

Backflashover at 300 m from the substation  
on the 4th connected 150 kV line



# TRV STUDY AT A 345 kV SUBSTATION

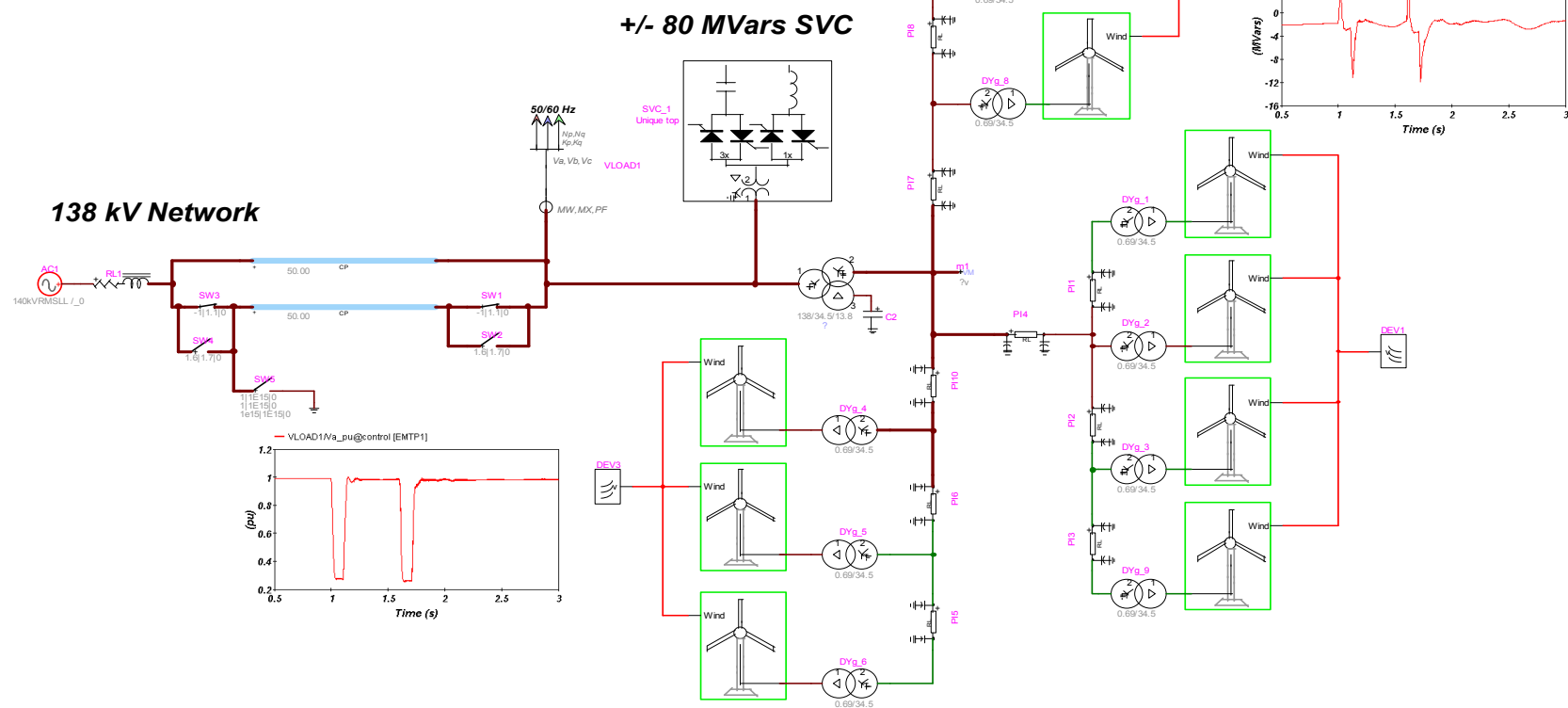


EMTP-RV

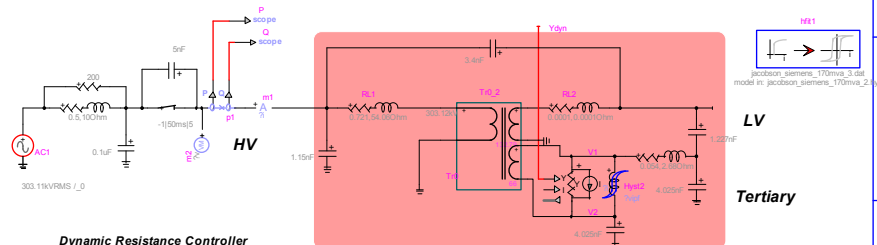




## 200 MW Wind Farm Integration Study



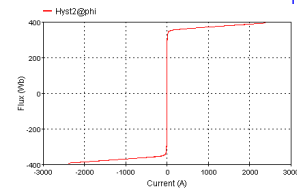
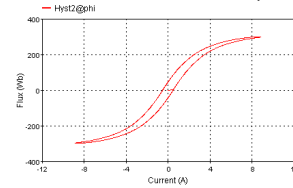
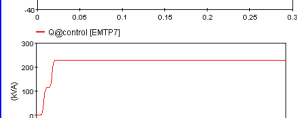
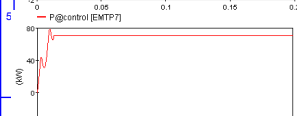
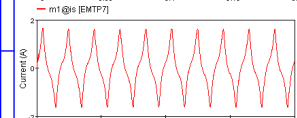
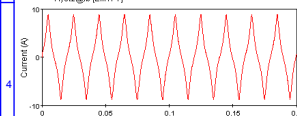
## ***Ferroresonance Study***



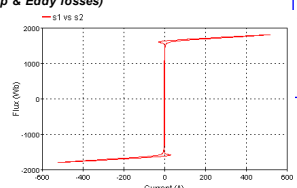
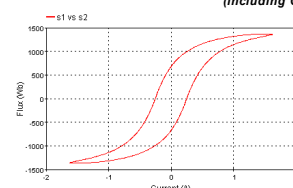
### Dynamic Resistance Controller Modeling Eddy losses



**Modeled Hysteresis Characteristic  
at 1.0 & 1.4 pu**



**Obtained HV Hysteresis  
Characteristic at 1.0 & 1.4pu  
(including Cap & Eddy losses)**



**Simulated Saturation Characteristic**  
(Air reactance of 45.8%)

$$X_m @ 1.0 \text{ pu} = 300 \text{ kOhms}$$

**Air reactance=44.3% @ 170 MVA**

| Vm2 rms in pu of 303.11 kV | Im1 (rms) in pu of 170 MVA |
|----------------------------|----------------------------|
| 1.2                        | 0.021                      |
| 1.3                        | 0.180                      |
| 1.4                        | 0.406                      |

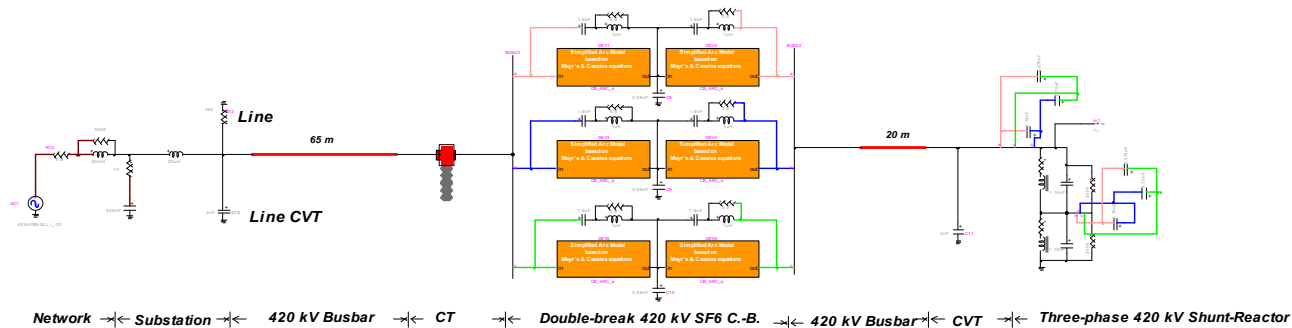


## Switching of A 420 kV Three-Phase Shunt-Reactor

10 FILES

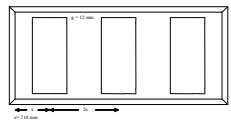
State of the art simulation introducing:

- A realistic model of a three-phase shunt reactor taking into account the asymmetrical couplings of the magnetic circuit;
- A realistic circuit-breaker model based on the well-known Cassie - Mayr modified arc equations;



Three-Phase 420 kV 100 MVARs Shunt Reactor

$P = 0.548 \text{ Wb}$ ,  $N=1409 \text{ turns}$ ,  $L1=5.617 \text{ H}$

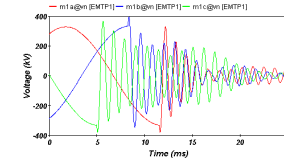
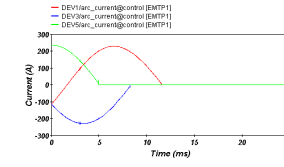
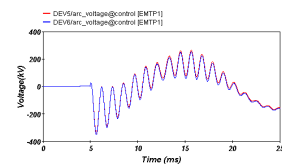
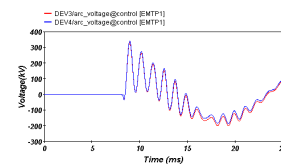
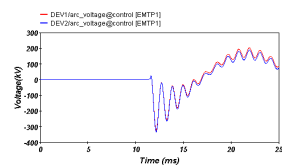


For  $\mu$  (50 Hz) = 0.06 H/m:

|                                 |
|---------------------------------|
| $X_{bc} = 0.02 \text{ } \Omega$ |
| $X_{ca} = 0.02 \text{ } \Omega$ |
| $X_{ab} = 0.02 \text{ } \Omega$ |
| $X_{bc} = 0.02 \text{ } \Omega$ |
| $X_{ca} = 0.02 \text{ } \Omega$ |
| $X_{ab} = 0.02 \text{ } \Omega$ |

For  $\mu$  (700 Hz) = 0.01 H/m:

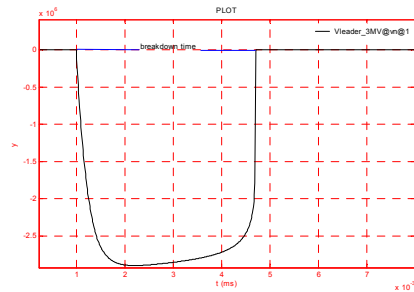
|                                 |
|---------------------------------|
| $X_{bc} = 0.02 \text{ } \Omega$ |
| $X_{ca} = 0.02 \text{ } \Omega$ |
| $X_{ab} = 0.02 \text{ } \Omega$ |
| $X_{bc} = 0.02 \text{ } \Omega$ |
| $X_{ca} = 0.02 \text{ } \Omega$ |
| $X_{ab} = 0.02 \text{ } \Omega$ |



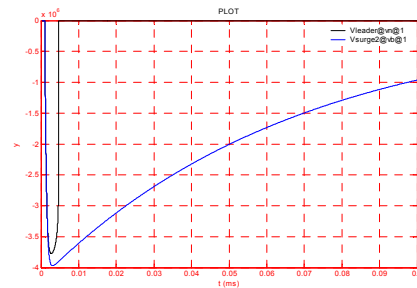
EMTP-RV



## Validation of the Air gap leader Model with CIGRE equation



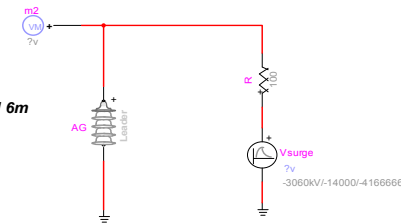
breakdown time definition



A typical leader breakdown voltage compared to the applied surge voltage

NO FILES

The leader length varies between 3 and 6m



The applied surge varies between -3 and -5MV

| Voltage(MV) | Length (m) |       |          |       |          |       |          |       |
|-------------|------------|-------|----------|-------|----------|-------|----------|-------|
|             | 3          |       | 4        |       | 5        |       | 6        |       |
|             | Equation   | Model | Equation | Model | Equation | Model | Equation | Model |
| 3           | 1.2516     | 1.69  | 2.568    | 2.9   | 5.4155   | 4.8   |          |       |
| 4           | 0.6944     | 0.95  | 1.2516   | 1.58  | 2.1491   | 2.15  | 3.6902   | 3.1   |
| 5           | 0.4622     | 0.69  | 0.7867   | 1.1   | 1.2516   | 1.3   | 1.9316   | 1.8   |

breakdown time comparison in us

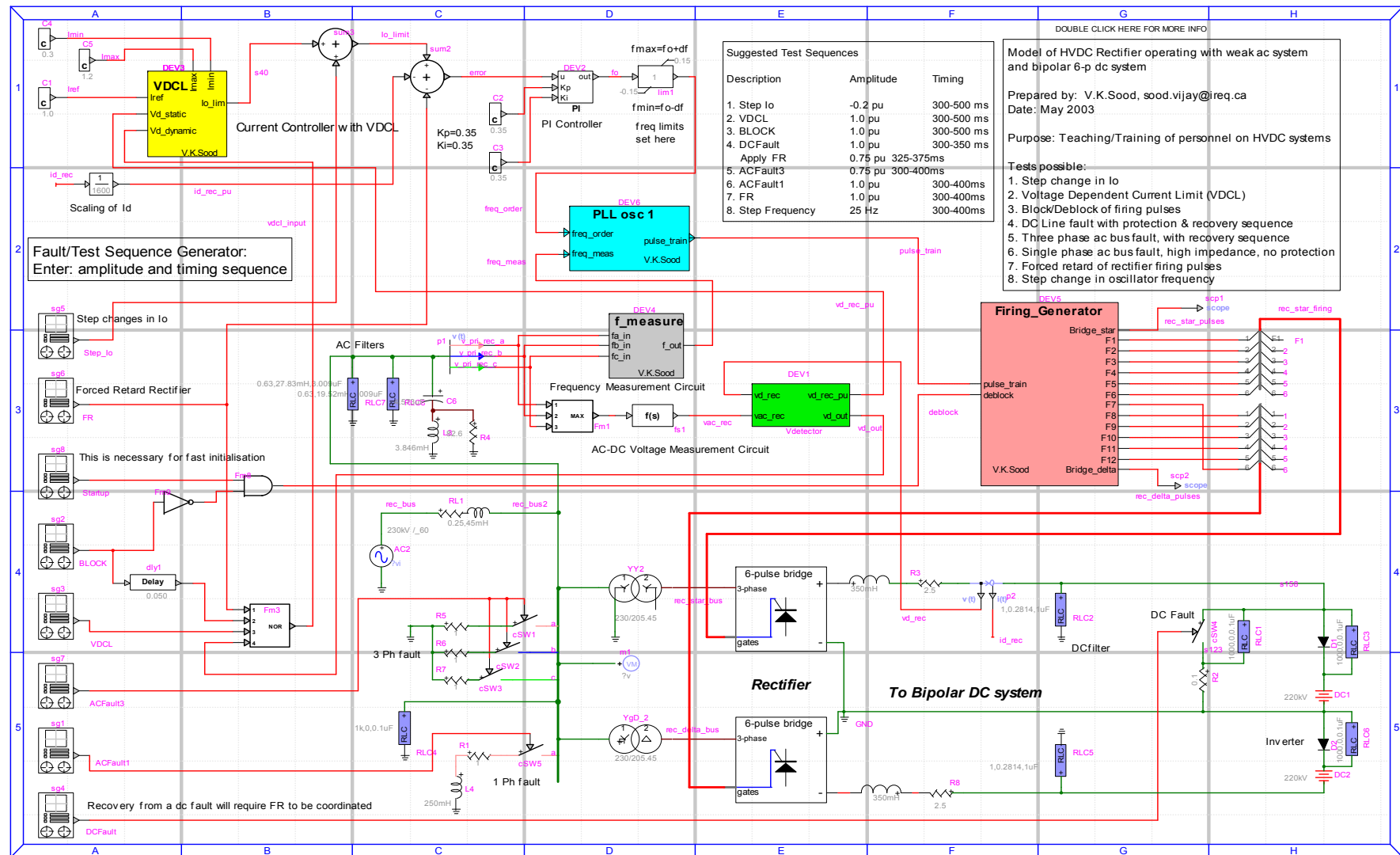
Ref:

1- Shindo, Takatoshi; Suzuki, Toshio (CRIEPI) " New Calculation Method of Breakdown Voltage-Time Characteristics of Long Air Gaps", IEEE Transactions on Power Apparatus and Systems, Vol. PAS-104, No. 6, June 1985, pp 1556-1563.

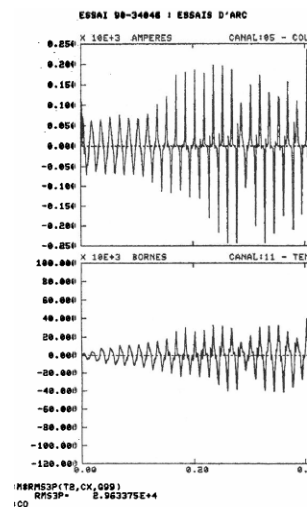
2- DARVENIZA(M.); POPOLANSKY (F.); WHITEHEAD (E.R.) "Lightning protection of UHV transmission lines", CIGRE report 1975-41.





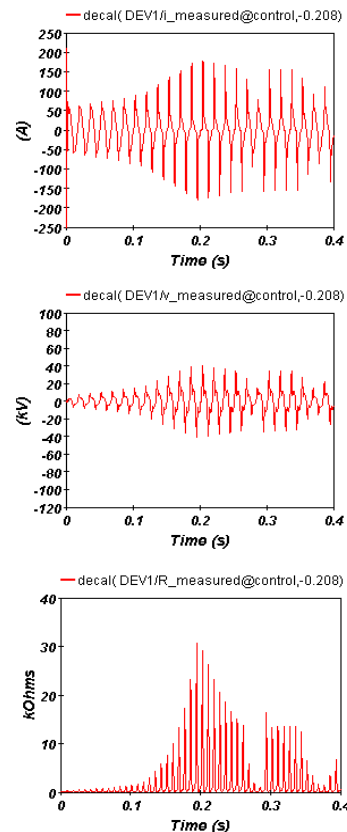


### Field Recording (10-08-1986)

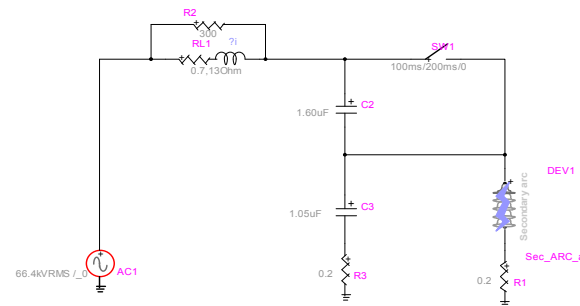


IO FILES

### EMTP-RV Simulation (05-22-2005)



### Validation of the Secondary Arc Model with IREQ Laboratory Tests

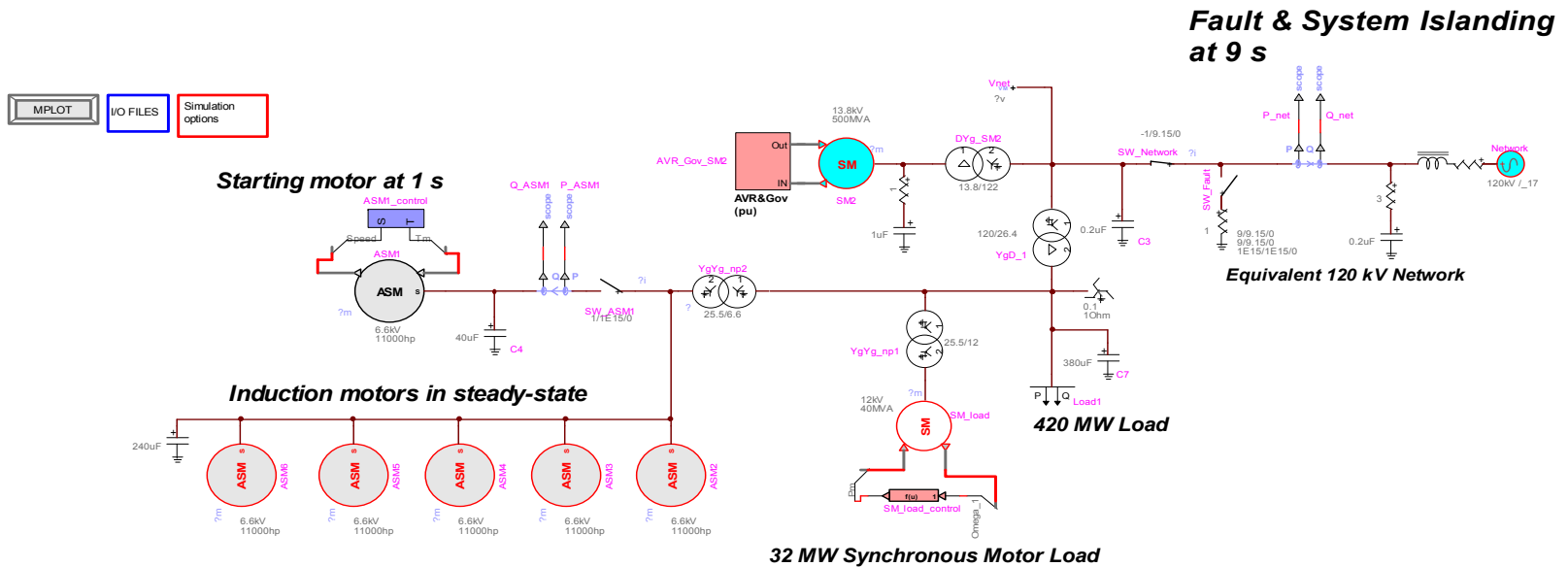


**Primary Arc: 5 kA eff**  
**Secondary Arc: 40 A**  
**Wind Speed: 9.7 km/h**  
**Secondary Arc Duration: 1.04 sec.**  
**315 kV insulator string, l=2.3 m**

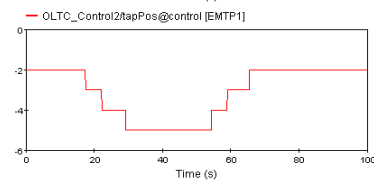
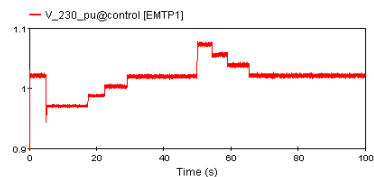
**Ref.: Kizilcay M., Bán G., Prikler L., Handl P.: "Interaction of the Secondary Arc with the Transmission System during Single-Phase Autoreclosure" IEEE Bologna PowerTech Conference, June 23-26, 2003 Bologna, Italy, Paper 471**

## Example of Synchronous/Asynchronous Machine Modeling

- Starting an 11000 hp motor at 1 s with 5 induction machines already in steady-state
- LL-g fault on the 120 kV bus with system islanding at 9 s
- System recovery by the governor system of the large SM until 30 s
- Case showing the good numerical stability of large number of machines in EMTP-RV
- Ref. (Motor): G. J. Rogers, *IEEE Trans. on Energy Conversion*, Vol. EC2, No 4 Dec. 1987, pp. 622-628.
- Using variable output rate after 15 s of simulation.

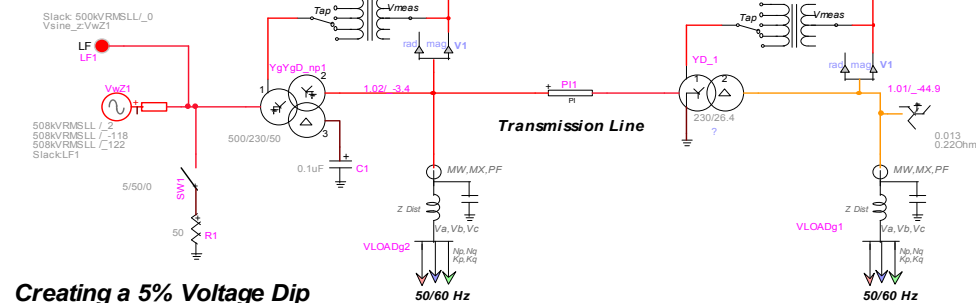
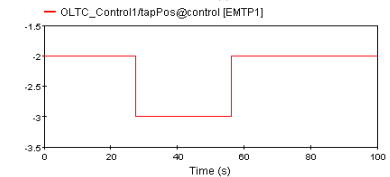
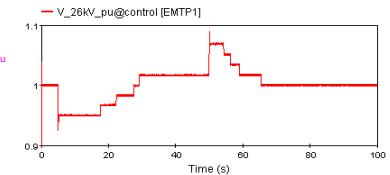


## Operation of Tap Changers During a Voltage Dip



**$\pm 10\%$  of 230 kV  
in 6 taps of 1.667%  
Initial Tap at -2  
 $Td0=10$  s,  $Td$  inverse  
Deadband of 1%**

**$\pm 15\%$  of 26.4 kV  
in 8 taps of 1.875%  
Initial Tap at -2  
 $Td0=15$  s,  $Td$  inverse  
Deadband of 1.5%**



**Creating a 5% Voltage Dip  
Duration of 45 sec.**

IO FILES

MPLT

EMTP-RV





## ZnO Arrester model based on IEEE Surge Protective Device Working Group

- $L1$  ( $\mu\text{H}$ ) = 15 d/n;  $R1$  ( $\Omega$ ) = 65 d/n
- $L0$  ( $\mu\text{H}$ ) = 0.2 d/n;  $R0$  ( $\Omega$ ) = 100 d/n
- $C0$  (pF) = 100 n/d

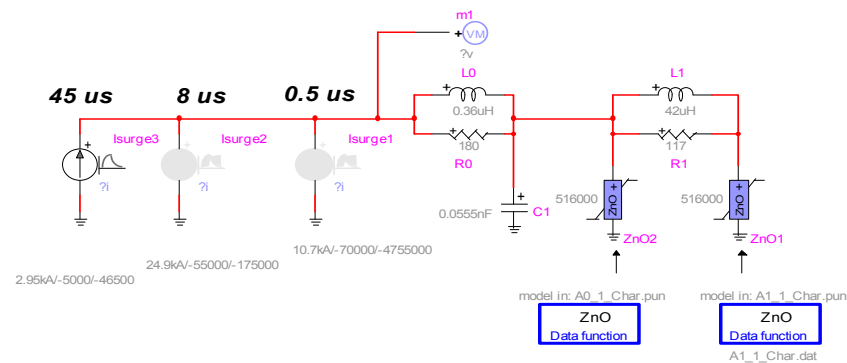
$d$  is the Height of the arrester and  $n$  is the number of parallel columns

Simulation options

I/O FILES

**Example of Modeling of an Ohio-Brass ZnO Arrester for a 330 kV Network**  
**MCOV= 209 kV**  
 **$d=1.8$  m,  $n=1$**

**A0 & A1 Characteristics adjusted to get 516 kV for a 2 kA 45  $\mu\text{s}$  Switching Surge then  $L1$  adjusted to get 604 kV for a 10 kA 8/20  $\mu\text{s}$  Lightning surge then checking for 10 kA 0.5  $\mu\text{s}$  front of wave 664.5 kV vs 665 kV from Ohio-Brass FANTASTIC!!**

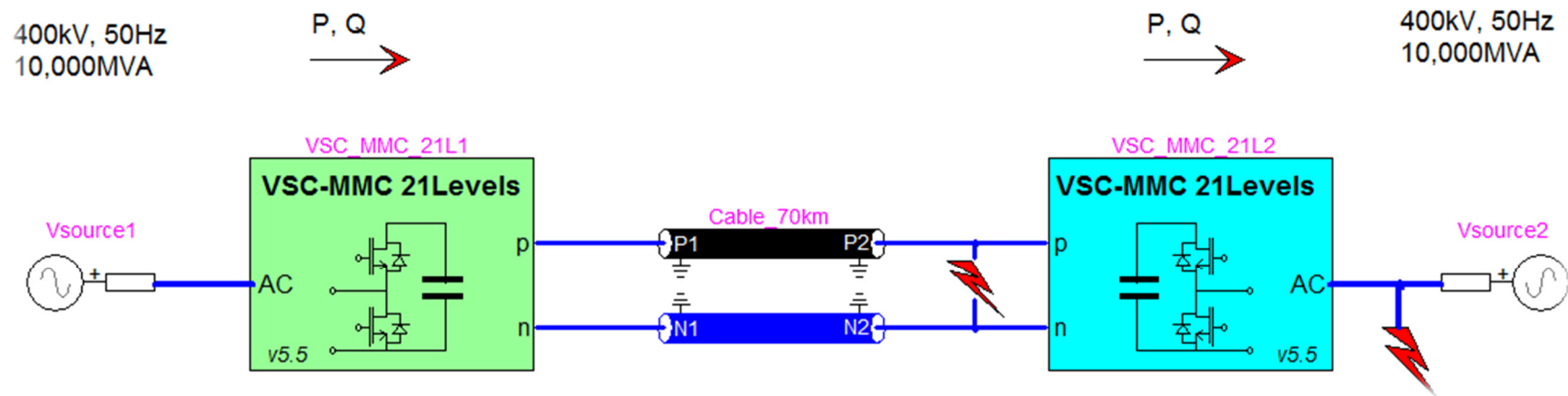


## New example

### HVDC VSC-MMC transmission system 1,000 MVA (+/- 320kV DC)

*Double Click here to access  
the User Guide of VSC-MMC model*

*Double Clcik here to access  
the Description of HVDC MMC model*

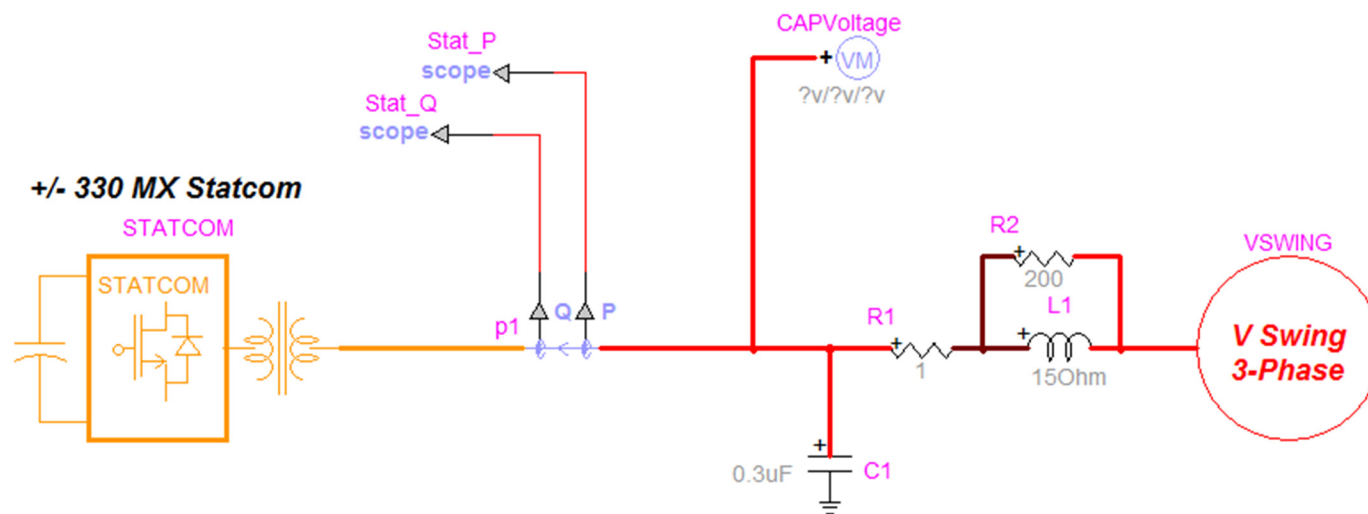


EMTP-RV



## New example

### Testing the Statcom Reactive Power Compensation During a Severe Voltage Swing

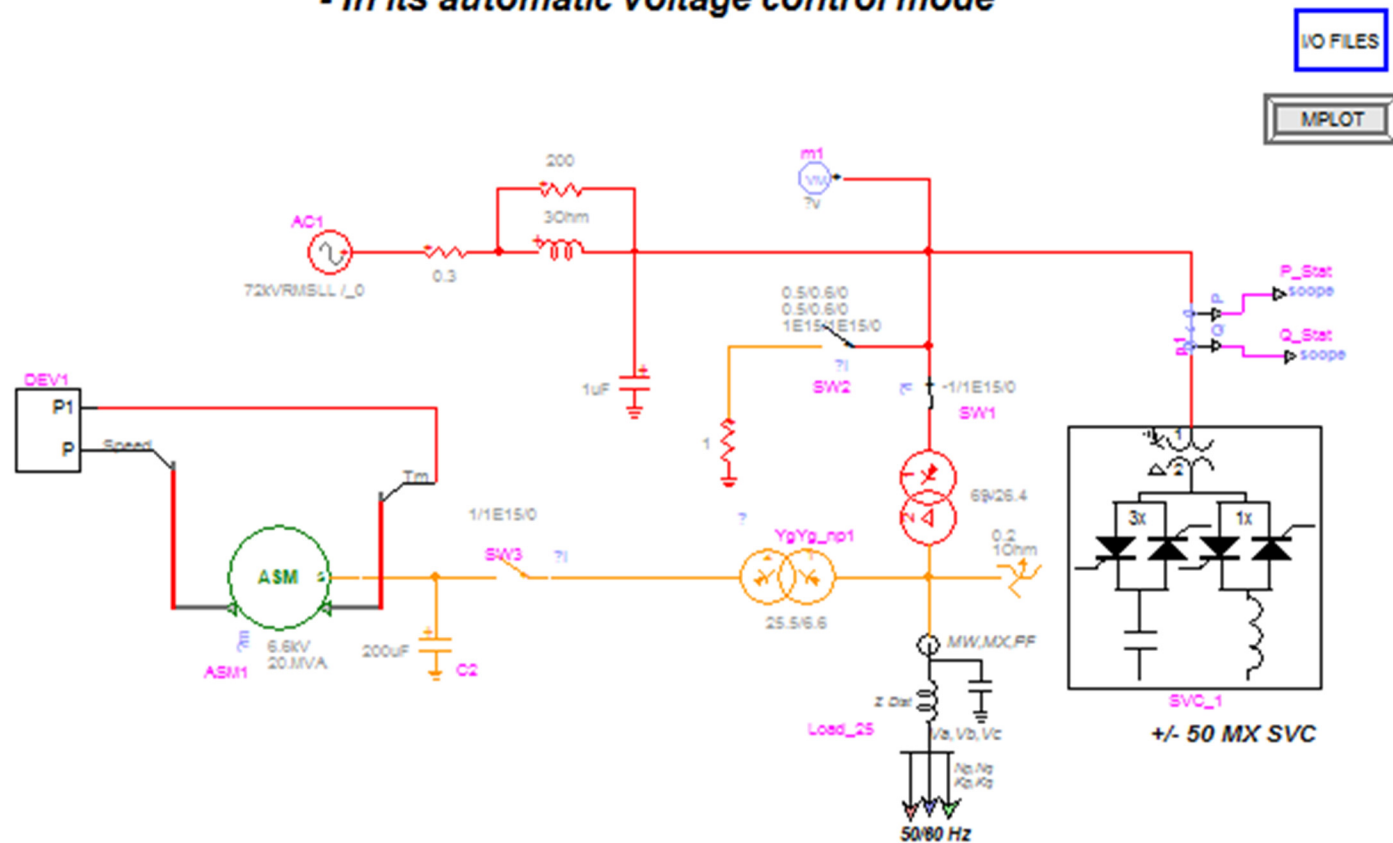


## New example

### Static Var Compensator Model

Testing the SVC behavior:

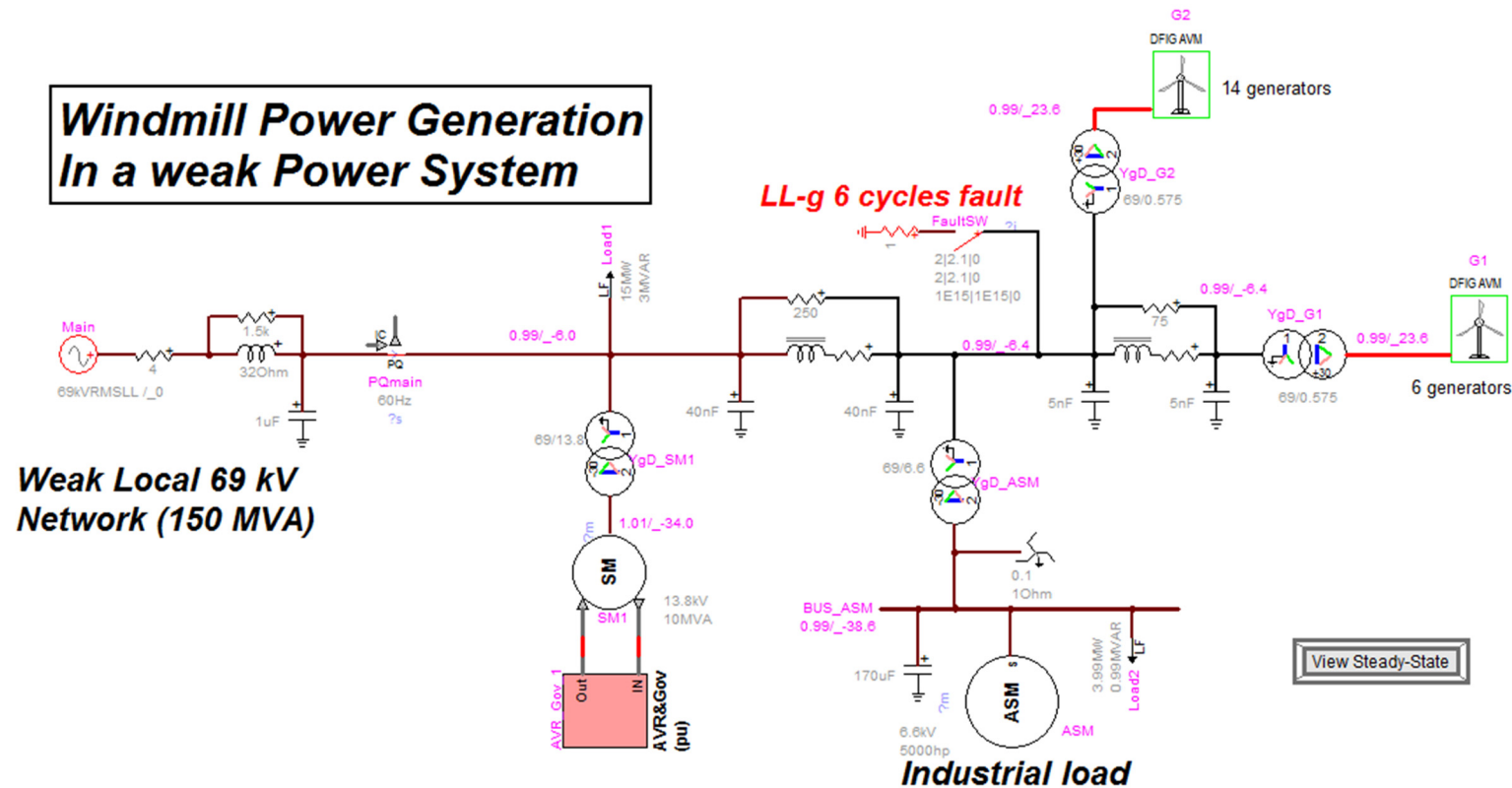
- During faults and harmonic distortions due to transformer saturation
- In its automatic voltage control mode





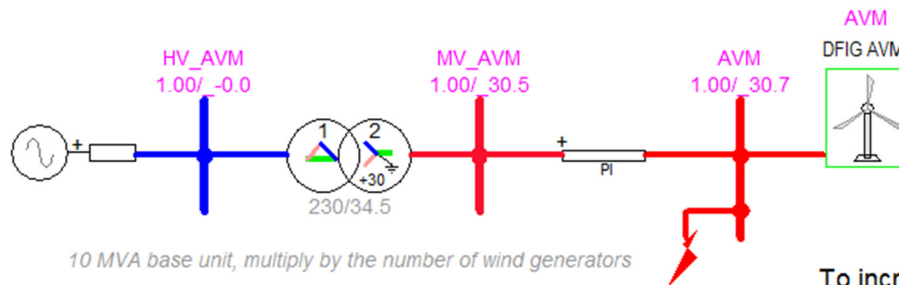
# New example

## Windmill Power Generation In a weak Power System

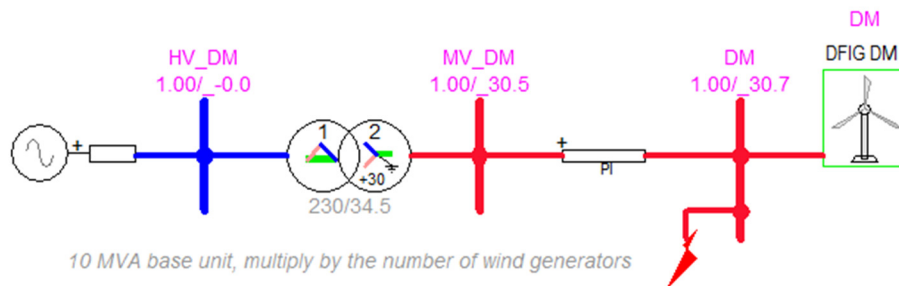


# New example

Comparison of Detailed model (DM) and Average value model (AVM), DFIG-type wind generator.  
The numerical integration time-step can be increased if the AVM is used alone in a network simulation.



To increase the number of wind generators for aggregation, see documentation in the mask script of the wind generator device.



# Contacts

Technical Support: [support@emtp.com](mailto:support@emtp.com)

Sales Team: [sales@emtp.com](mailto:sales@emtp.com)



**EMTP-RV**

The reference for power systems transients

[www.emtp.com](http://www.emtp.com)

**EMTP-RV**



**POWERSYS****Corporate headquarters**

Les Jardins de l'Entreprise  
13610 Le Puy-Sainte-Réparate  
FRANCE

Sales Email:

[sales@emtp.com](mailto:sales@emtp.com)

Support Email:

[support@emtp.com](mailto:support@emtp.com)

Tel: +33 (0)4 42 61 02 29

Fax: +33 (0)4 42 50 58 90

**POWERSYS****German Office**

Verbindungsbüro Deutschland  
Walter-Kolb-Str. 9-11  
60594 Frankfurt/Main  
DEUTSCHLAND

Email:

[vertrieb@powersys-solutions.com](mailto:vertrieb@powersys-solutions.com)

Tel. : +49 (0)69 / 96 21 76 - 34

Fax : +49 (0)69 / 96 21 76 - 20

**POWERSYS Inc.**

8401 Greenway Blvd. Suite 210.  
Middleton, WI 53562  
USA

Sales Email:

[sales.usa@emtp.com](mailto:sales.usa@emtp.com)

Support Email:

[support@emtp.com](mailto:support@emtp.com)

Tel : +1 608 203 8808

Fax: +1 608 203 8811

**CORPORATE WEB SITE:** [www.powersys-solutions.com](http://www.powersys-solutions.com)

